



---

# Lecture 6 Filtering in Frequency Domain

---

Guoxu Liu

Weifang University of Science and Technology

*liuguoxu@wfust.edu.cn*

November 6, 2020

# Outline

---

- ❑ Fourier Transform
- ❑ Filtering in Frequency Domain
- ❑ Smoothing Frequency Domain Filters
- ❑ Sharpening Frequency Domain Filters

# Fourier Transform

---

## □ 1D Fourier Transform

$$\mathfrak{F}\{f(x)\} = F(\omega) = \int_{-\infty}^{\infty} f(x) \exp[-j\omega x] dx$$

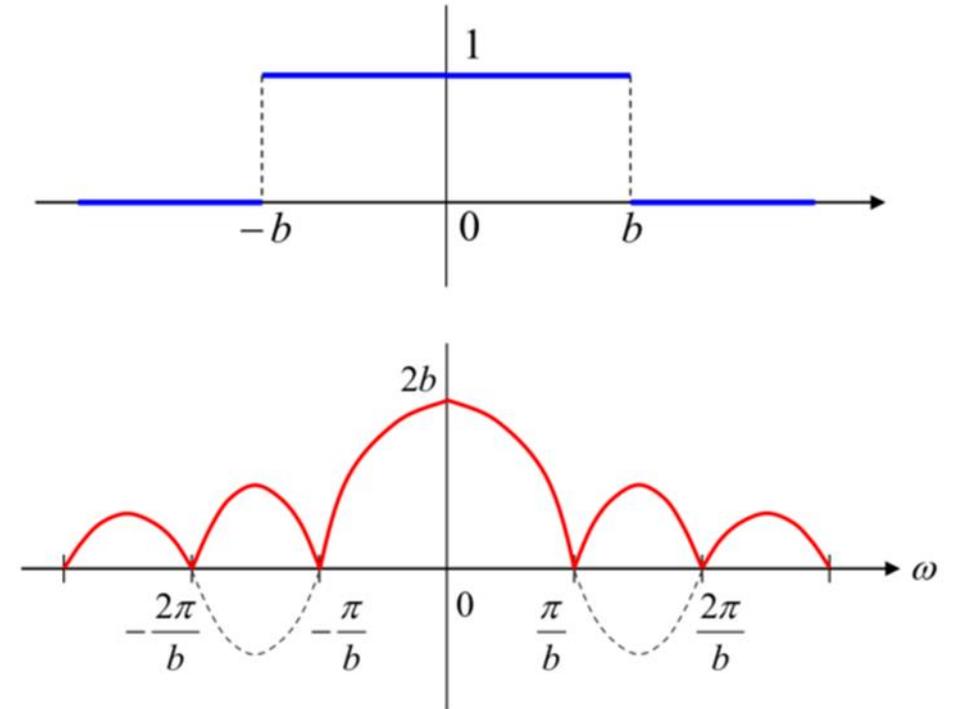
$$\mathfrak{F}^{-1}\{F(\omega)\} = f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) \exp[j\omega x] d\omega$$

# Fourier Transform

## □ Example 1

$$\begin{aligned} F(\omega) &= \int_{-\infty}^{\infty} f(x) \exp[-j\omega x] dx \\ &= \int_{-b}^b \exp[-j\omega x] dx \\ &= \int_{-b}^b (\cos \omega x - j \sin \omega x) dx \\ &= \frac{1}{\omega} [\sin \omega x]_{-b}^b = \frac{2}{\omega} \sin b\omega \end{aligned}$$

$$\frac{\sin b\omega}{b\omega} \quad \text{Sinc Function}$$



$$|F(\omega)| = 2b \left| \frac{\sin b\omega}{b\omega} \right|$$

Magnitude of complex number



$$F(u) = \int_{-\infty}^{\infty} f(x) \exp[-j2\pi ux] dx$$

$$f(x) = \int_{-\infty}^{\infty} F(u) \exp[j2\pi ux] du$$

$$\omega = 2\pi u \quad \Rightarrow \quad d\omega = 2\pi du$$

$$\begin{aligned} f(x) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) \exp[j\omega x] d\omega \\ &= \int_{-\infty}^{\infty} F(u) \exp[j2\pi ux] du \end{aligned}$$

## □ 2D Fourier Transform

$$F(u, v) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-j2\pi(ux+vy)} dx dy$$

$$f(x, y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} F(u, v) e^{j2\pi(ux+vy)} du dv$$

$$F(u, v) = \frac{1}{MN} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi(ux/M+vy/N)}$$

$$f(x, y) = \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} F(u, v) e^{j2\pi(ux/M+vy/N)}$$

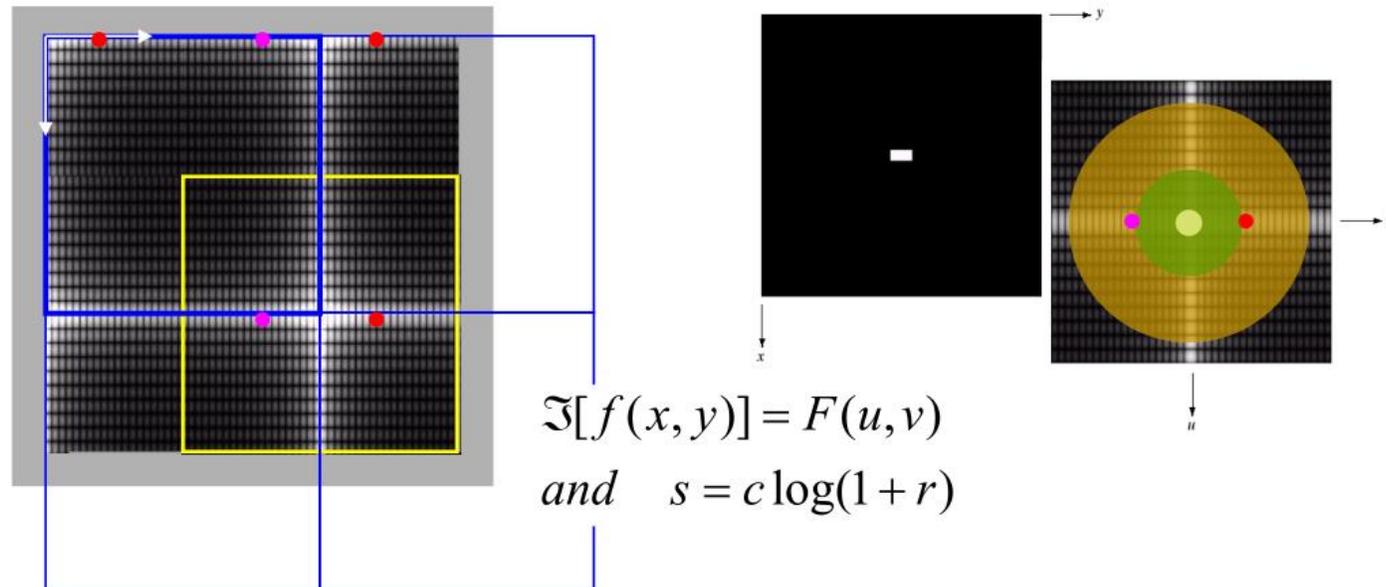
## □ Properties of 2D Fourier Transform

If  $f(x, y)$  is real,  $F(u, v) = F^*(-u, -v)$

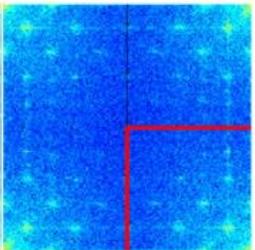
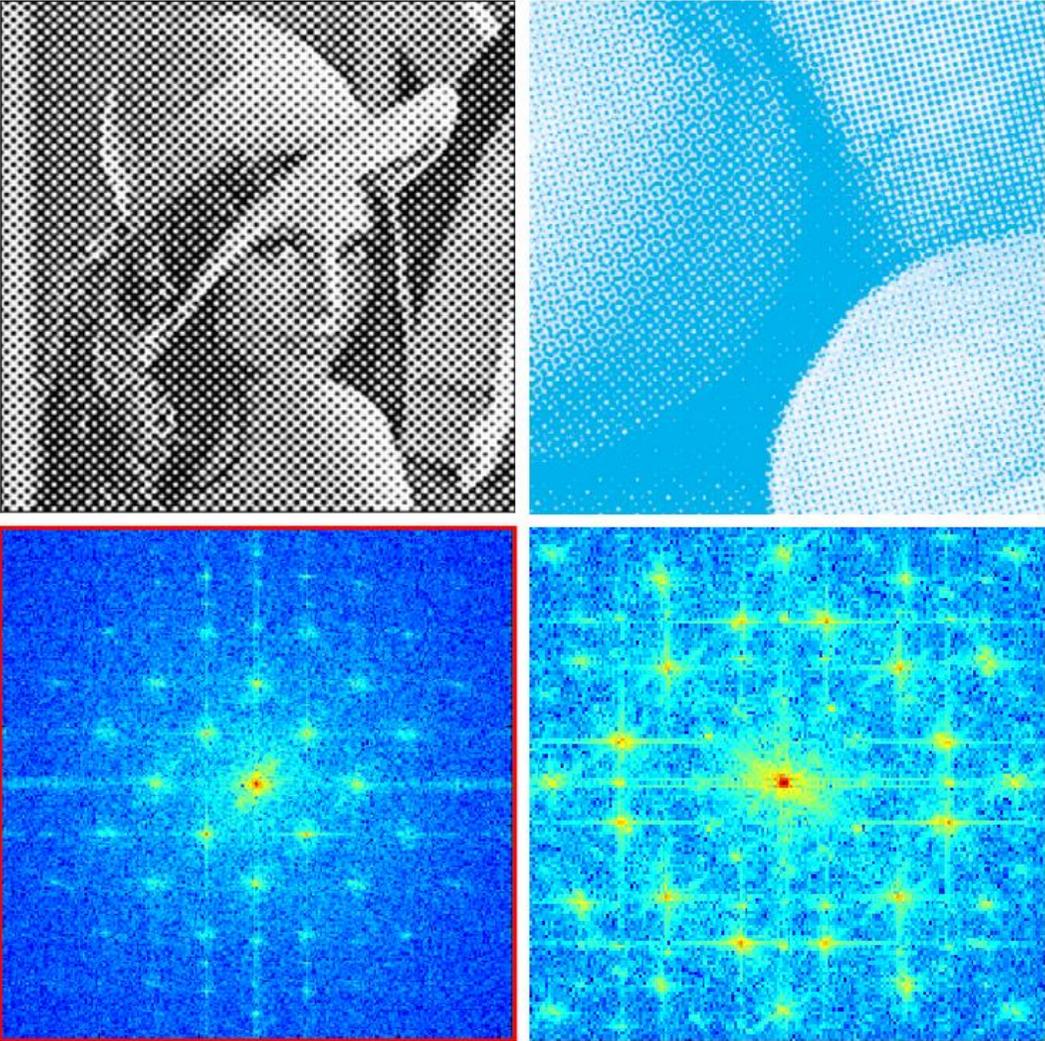
$$|F(u, v)| = |F(-u, -v)|$$

$$\mathfrak{F}[f(x, y)(-1)^{x+y}] = F(u - M/2, v - N/2)$$

$$\Delta u = \frac{1}{M\Delta x} \quad \& \quad \Delta v = \frac{1}{N\Delta y}$$

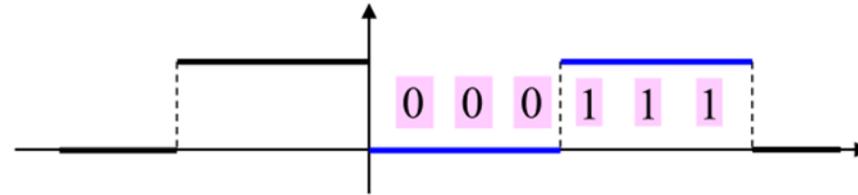


# Fourier Transform



# Fourier Transform

## □ 1D Case



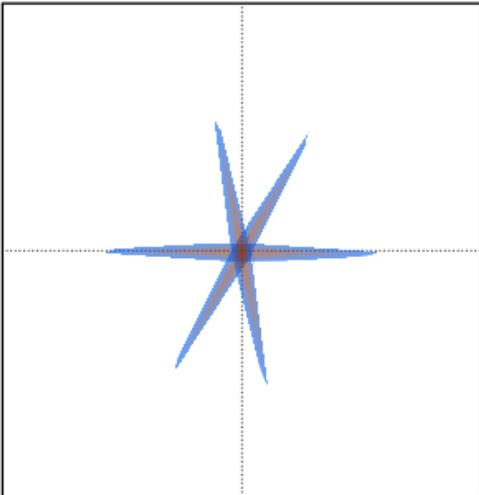
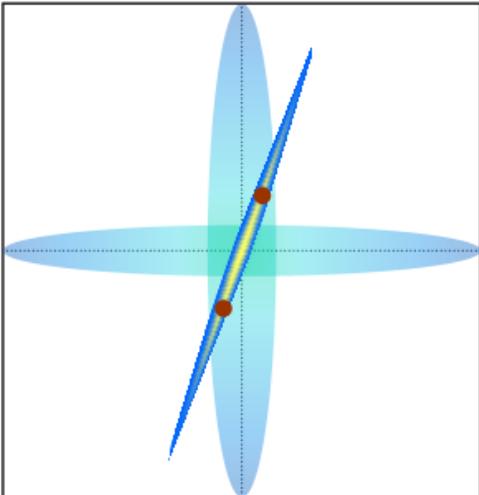
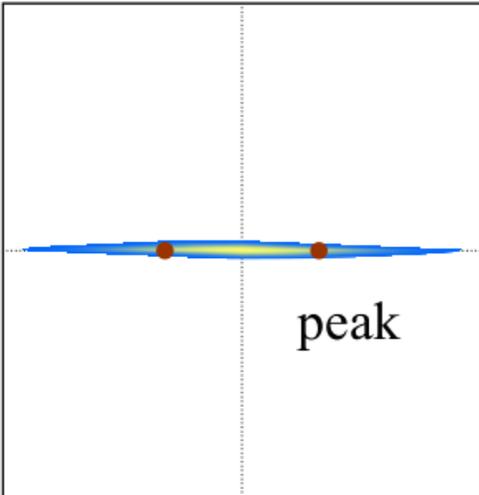
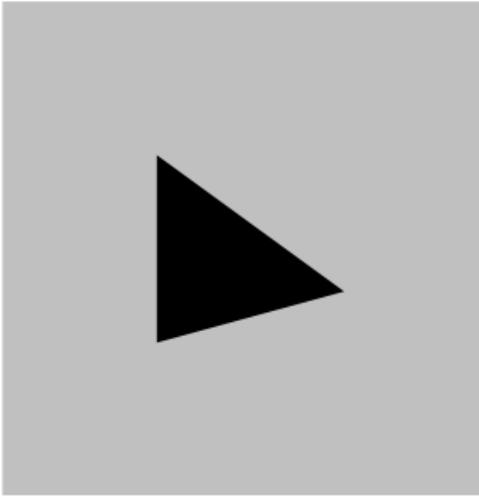
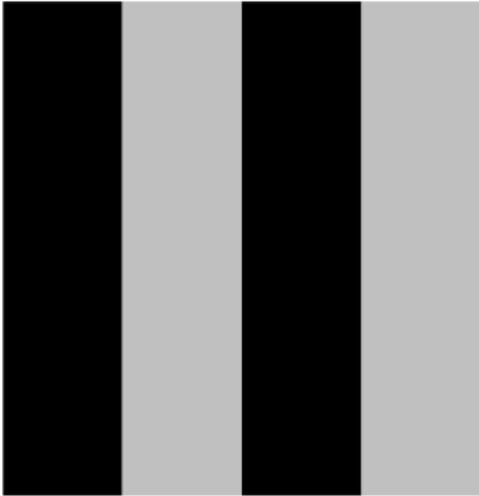
$$\begin{array}{cccccccccccccccc}
 f & 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 & 1 & 1 & 1 \\
 |F| & 3 & 2 & 0 & 1 & 0 & 2 & 3 & 2 & 0 & 1 & 0 & 2 & 3 & 2 & 0 & 1 & 0 & 2 \leftarrow (1/6)
 \end{array}$$

$$F[0 \ 1 \ 2 \ 3 \ 4 \ 5] = (1/6) \begin{bmatrix} 3 & -1+j\sqrt{3} & 0 & -1 & 0 & -1-j\sqrt{3} \end{bmatrix}$$

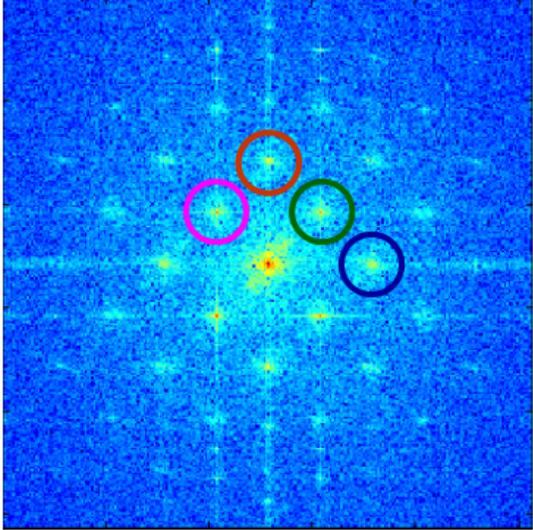
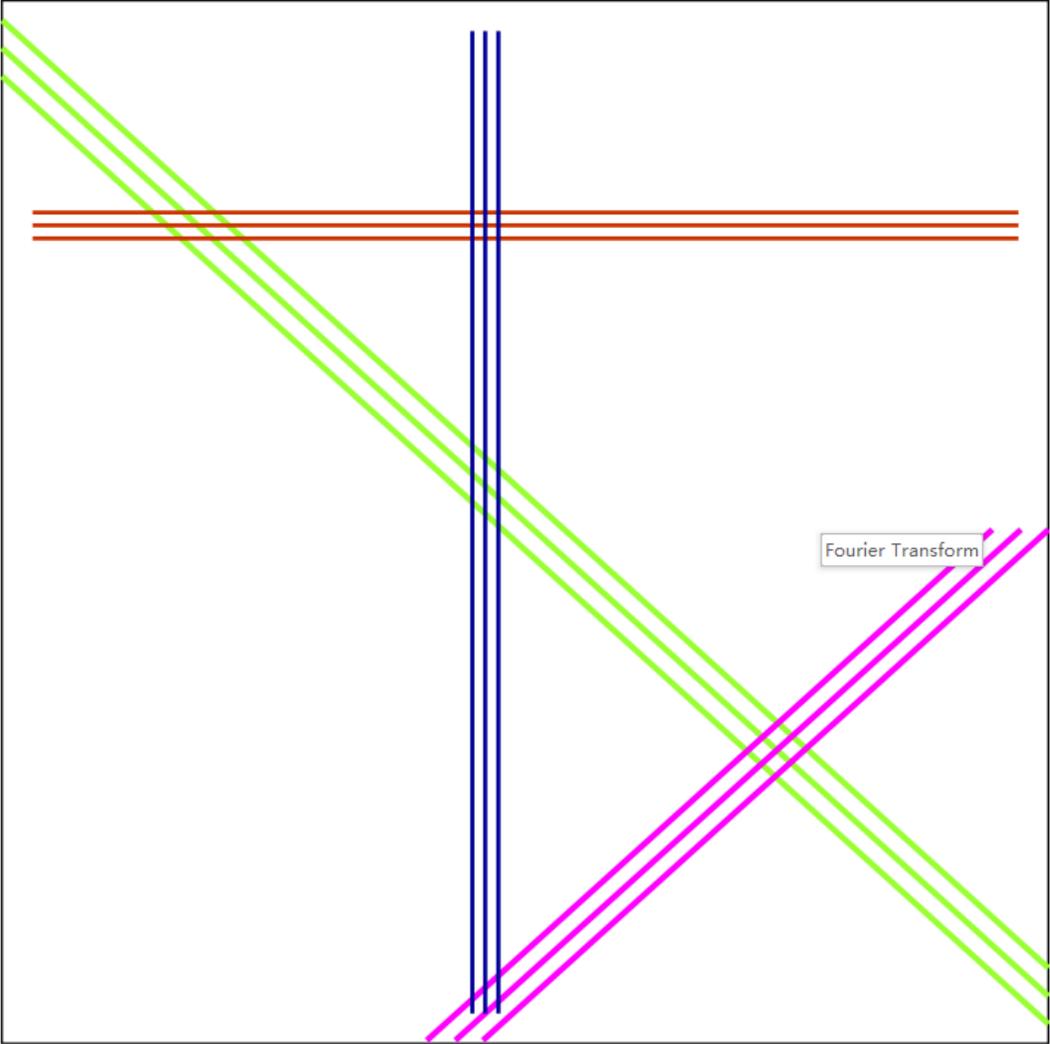
$$|F|[0 \ 1 \ 2 \ 3 \ 4 \ 5] = (1/6) \begin{bmatrix} 3 & 2 & 0 & 1 & 0 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 3 & -1+j\sqrt{3} & 0 & -1 & 0 & -1-j\sqrt{3} \end{bmatrix} \begin{bmatrix} 3 & -1+j\sqrt{3} & 0 & -1 & 0 & -1-j\sqrt{3} \end{bmatrix}$$

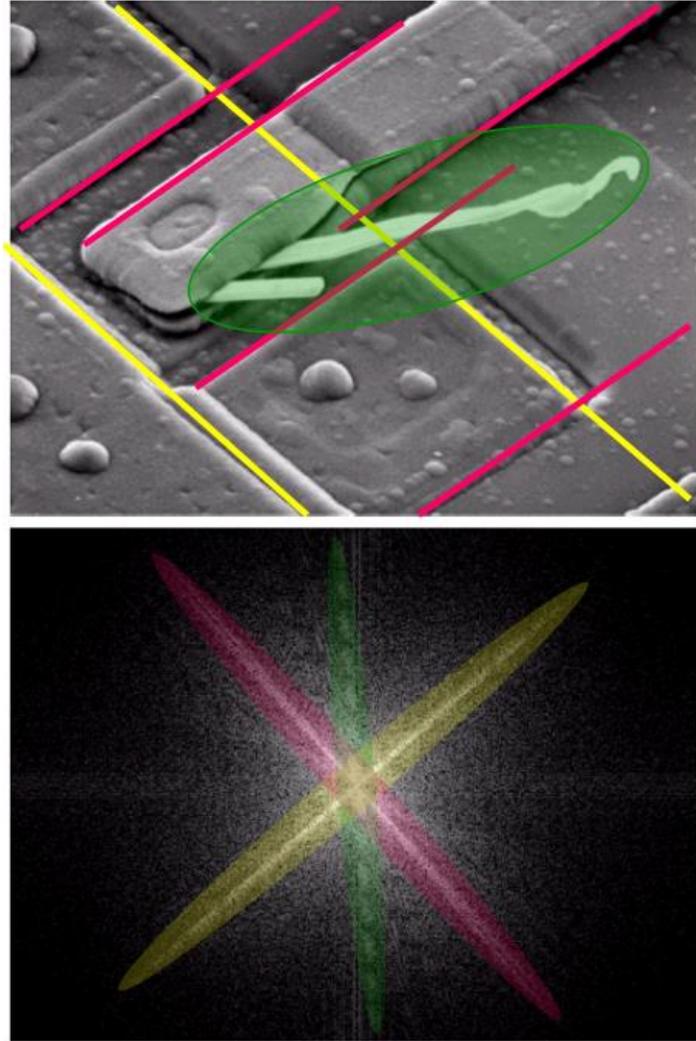
# Fourier Transform



# Fourier Transform

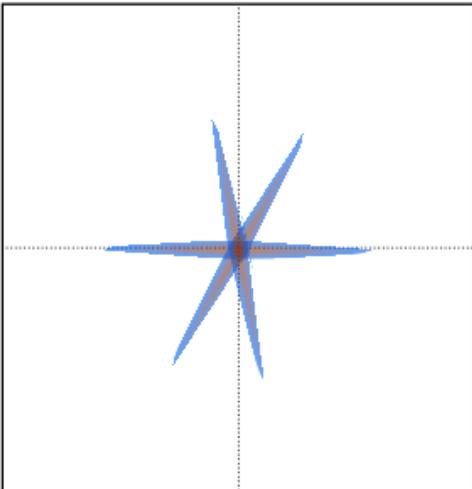
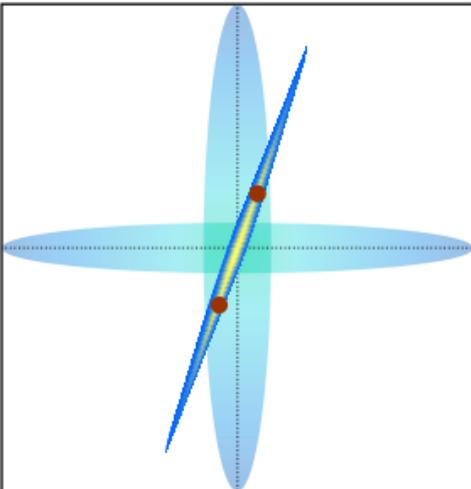
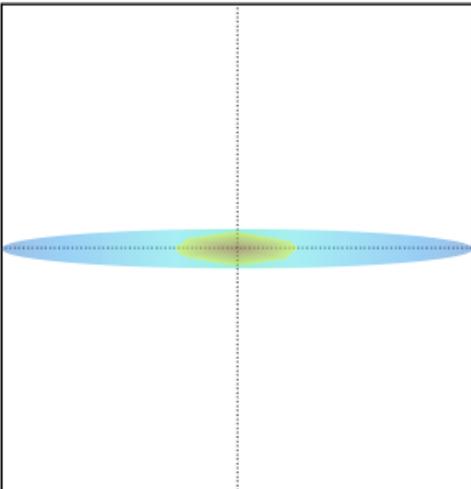
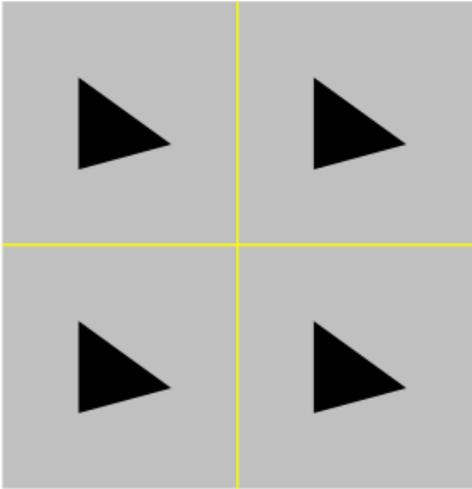
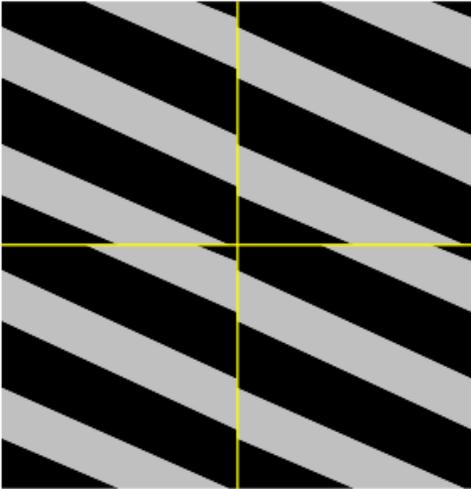
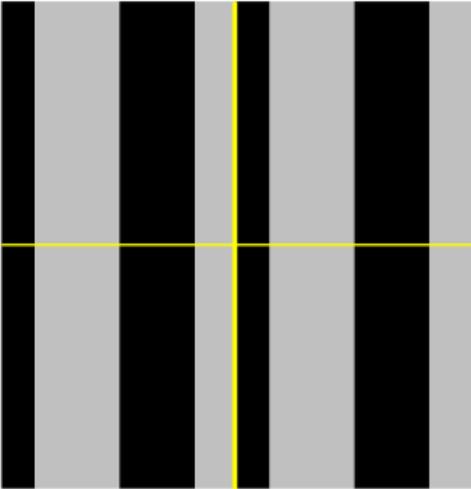


# Fourier Transform

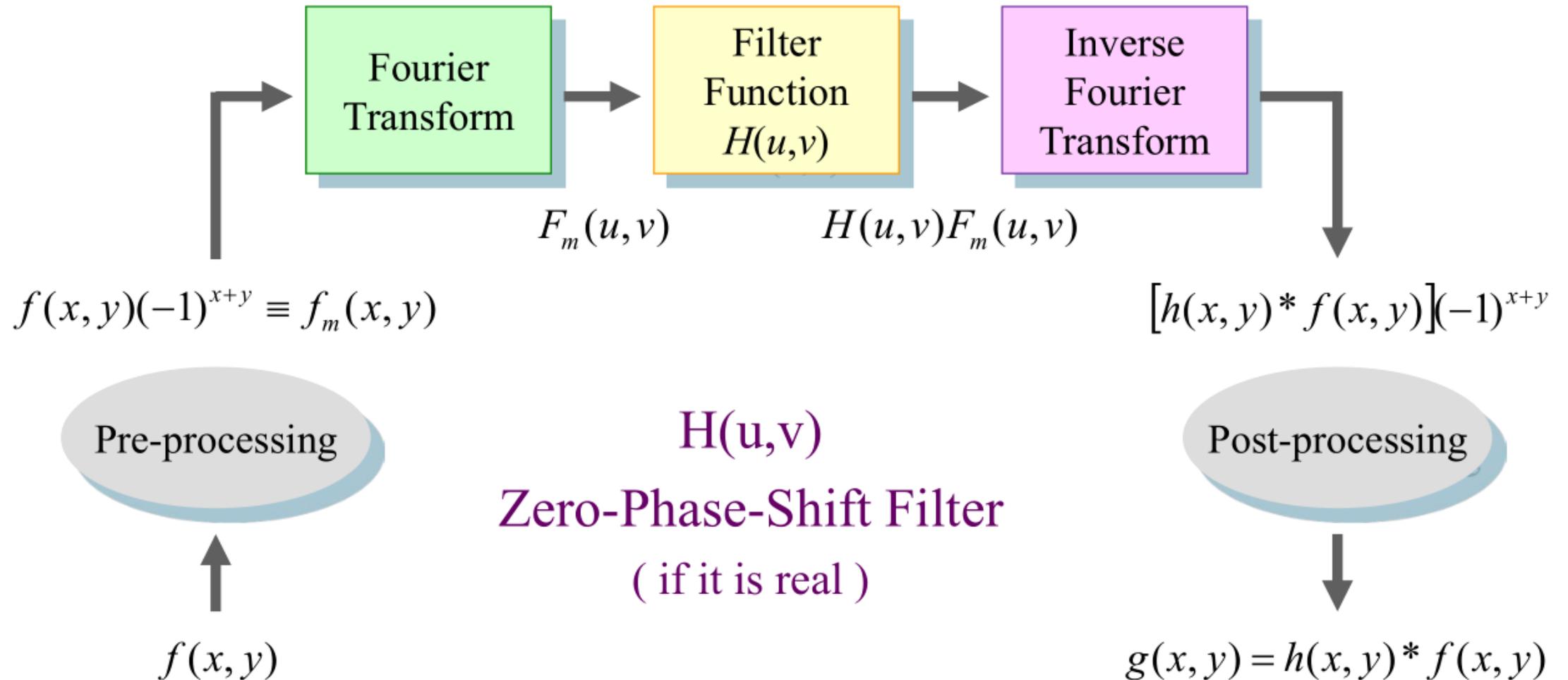


Note the zeros in vertical frequency components, corresponding to narrow span of the white protrusion

# Fourier Transform

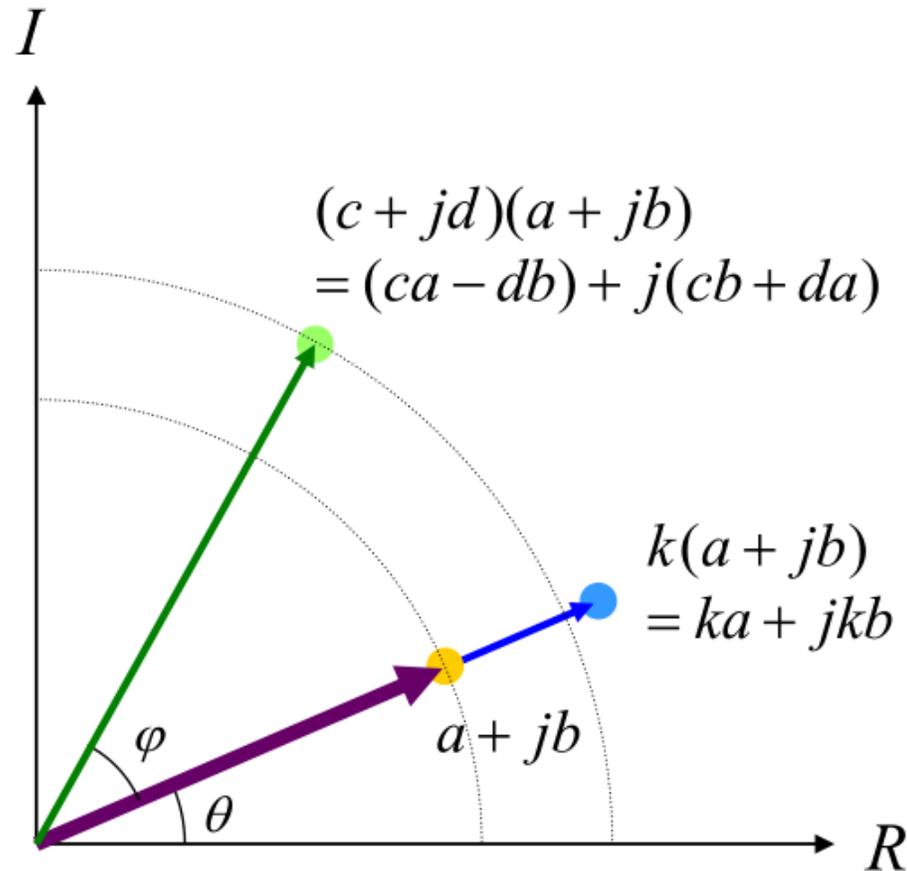


# Filtering in Frequency Domain



# Filtering in Frequency Domain

## Zero-Phase-Shift ?



$$a + jb = m_1 e^{j\theta}$$

$$c + jd = m_2 e^{j\varphi}$$

$$k(a + jb) = km_1 e^{j\theta} \quad k > 0$$

$$(c + jd)(a + jb) = m_1 m_2 e^{j(\theta + \varphi)}$$

# Filtering in Frequency Domain

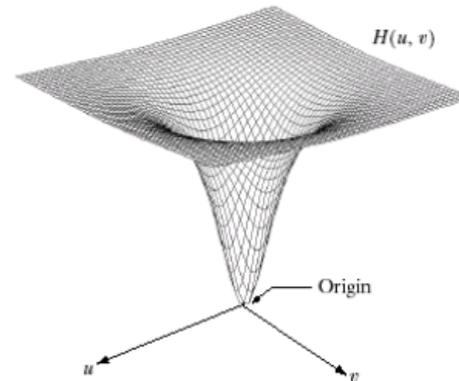
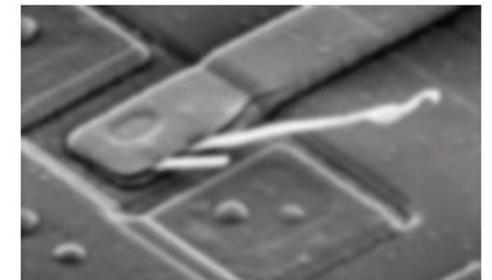
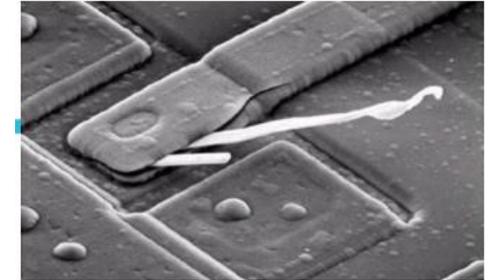
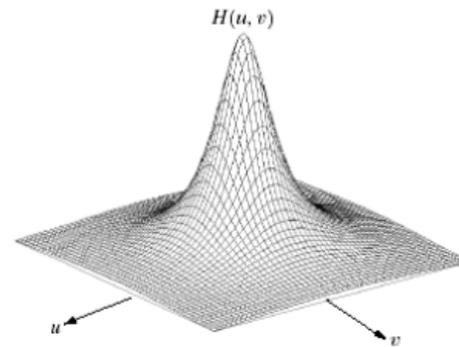
## Low Frequency

Responsible for general gray-level appearance of an image over smooth areas

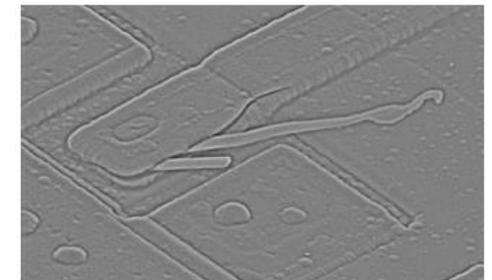
## High Frequency

Responsible for detail, such as edges and noise

### Lowpass Filter



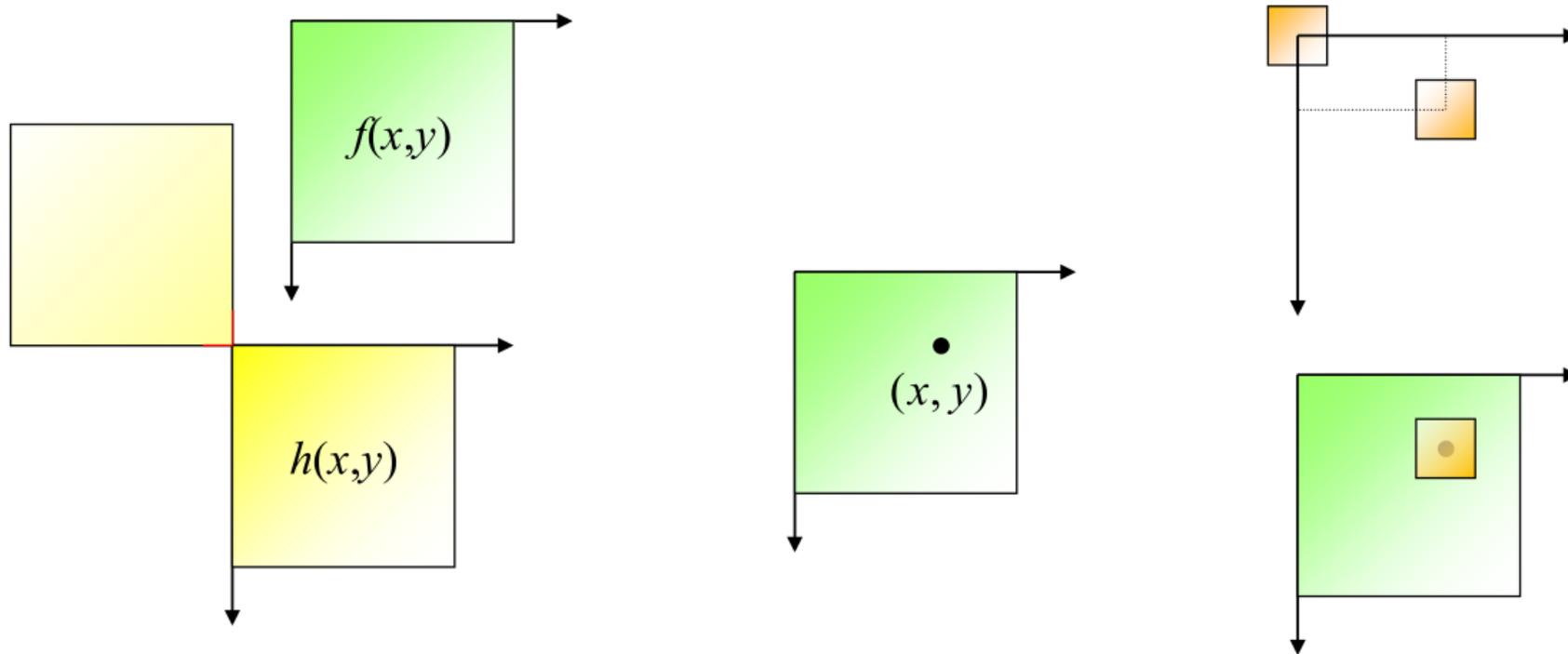
### Highpass Filter



# Filtering in Frequency Domain

## □ Convolution

$$f(x, y) * h(x, y) = \frac{1}{MN} \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} f(m, n) h(x-m, y-n)$$

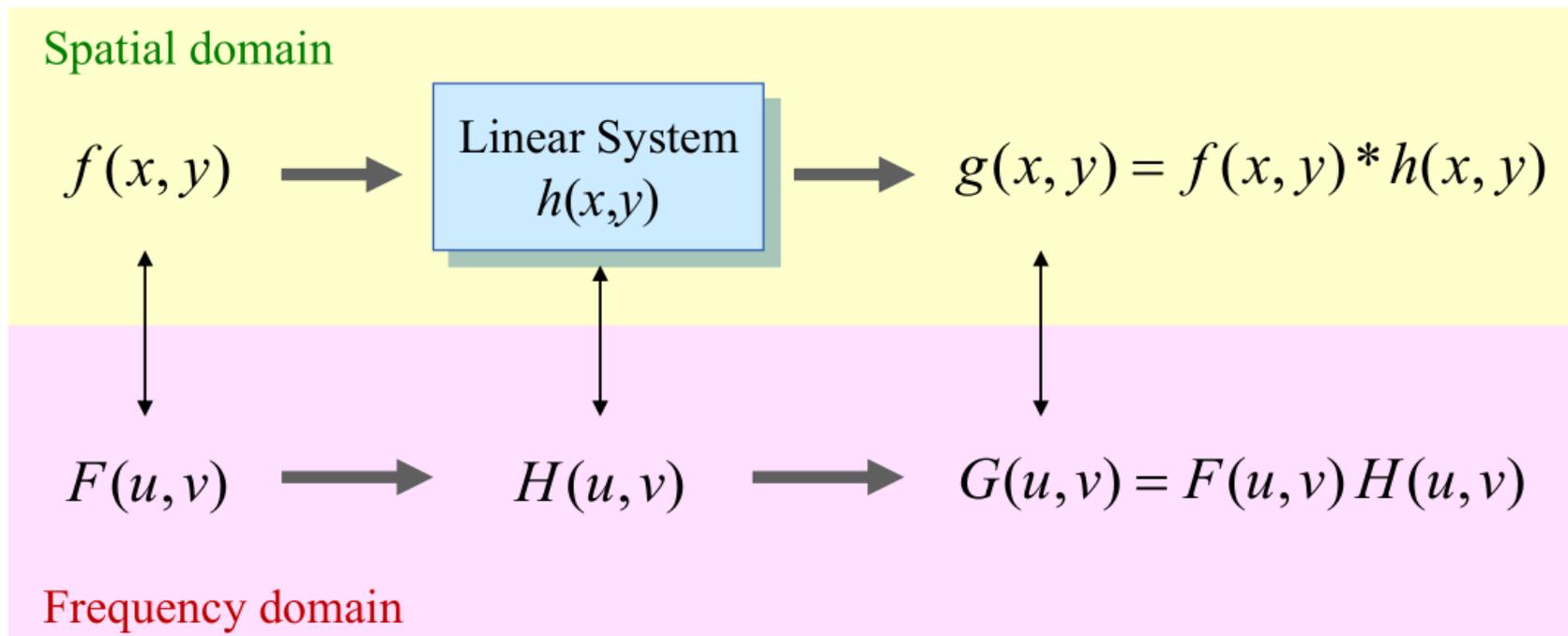


# Filtering in Frequency Domain

## □ Convolution Theorem

$$f(x, y) * h(x, y) \Leftrightarrow F(u, v)H(u, v)$$

$$f(x, y)h(x, y) \Leftrightarrow F(u, v) * H(u, v)$$



## □ Impulse Response

$$\sum_{x=0}^{M-1} \sum_{y=0}^{N-1} \delta(x - x_0, y - y_0) s(x, y) = s(x_0, y_0)$$

$$\Delta_{x_0, y_0}(u, v) = \frac{1}{MN} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} \delta(x - x_0, y - y_0) e^{-j2\pi(ux/M + vy/N)}$$

$$= \frac{1}{MN} e^{-j2\pi(ux_0/M + vy_0/N)}$$

$$\Delta_{0,0}(u, v) = \frac{1}{MN}$$

$$\delta(x - x_0, y - y_0) * h(x, y)$$

$$= \frac{1}{MN} \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} \delta(m - x_0, n - y_0) h(x - m, y - n)$$

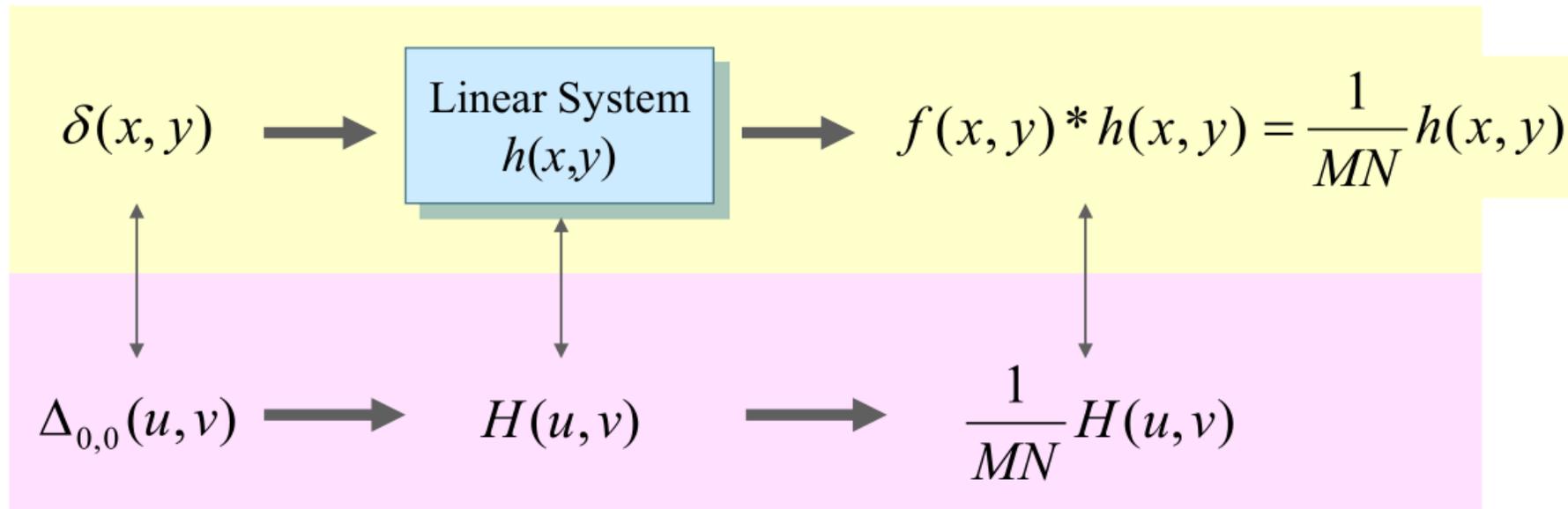
$$= \frac{1}{MN} h(x - x_0, y - y_0)$$

$$\delta(x, y) * h(x, y) = \frac{1}{MN} h(x, y)$$

# Filtering in Frequency Domain

## □ Impulse Response & Convolution Theorem

$$\delta(x, y) * h(x, y) \Leftrightarrow \Delta_{0,0}(u, v)H(u, v) = \frac{1}{MN}H(u, v)$$

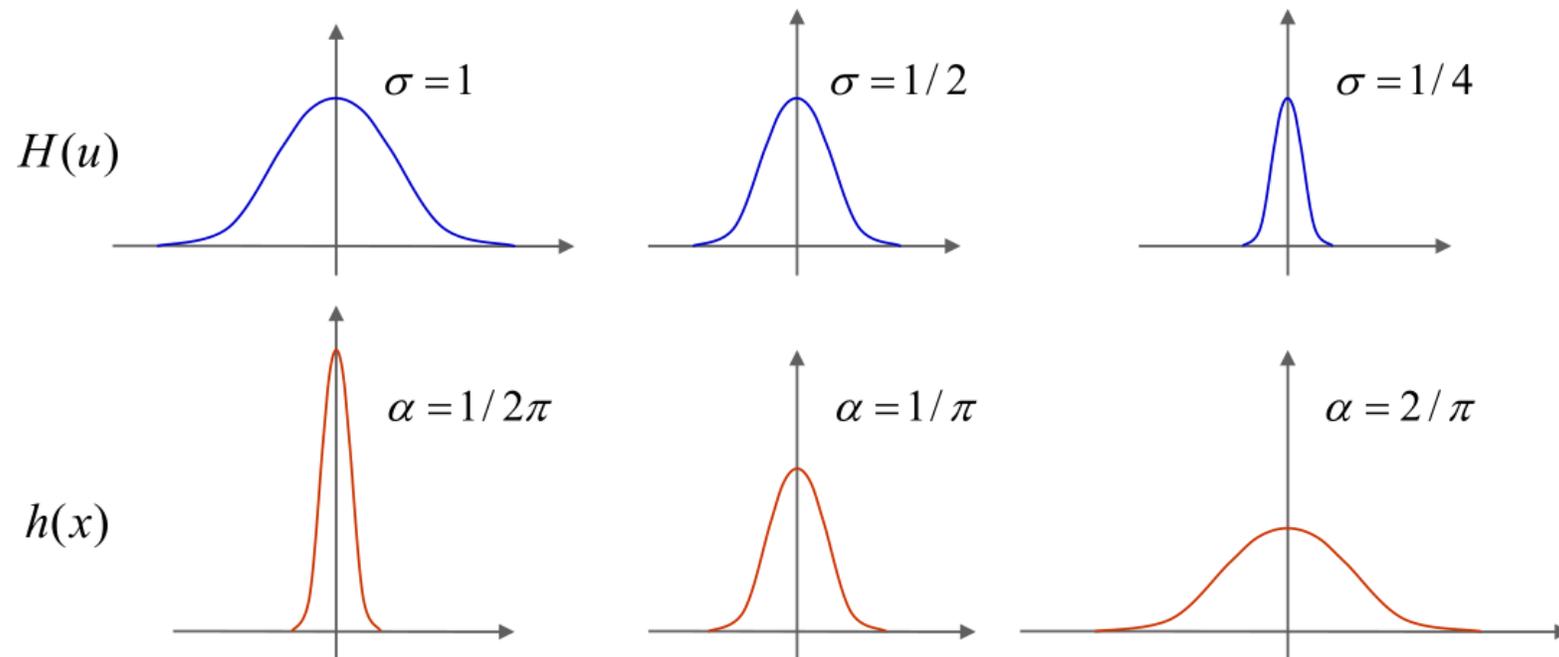


# Filtering in Frequency Domain

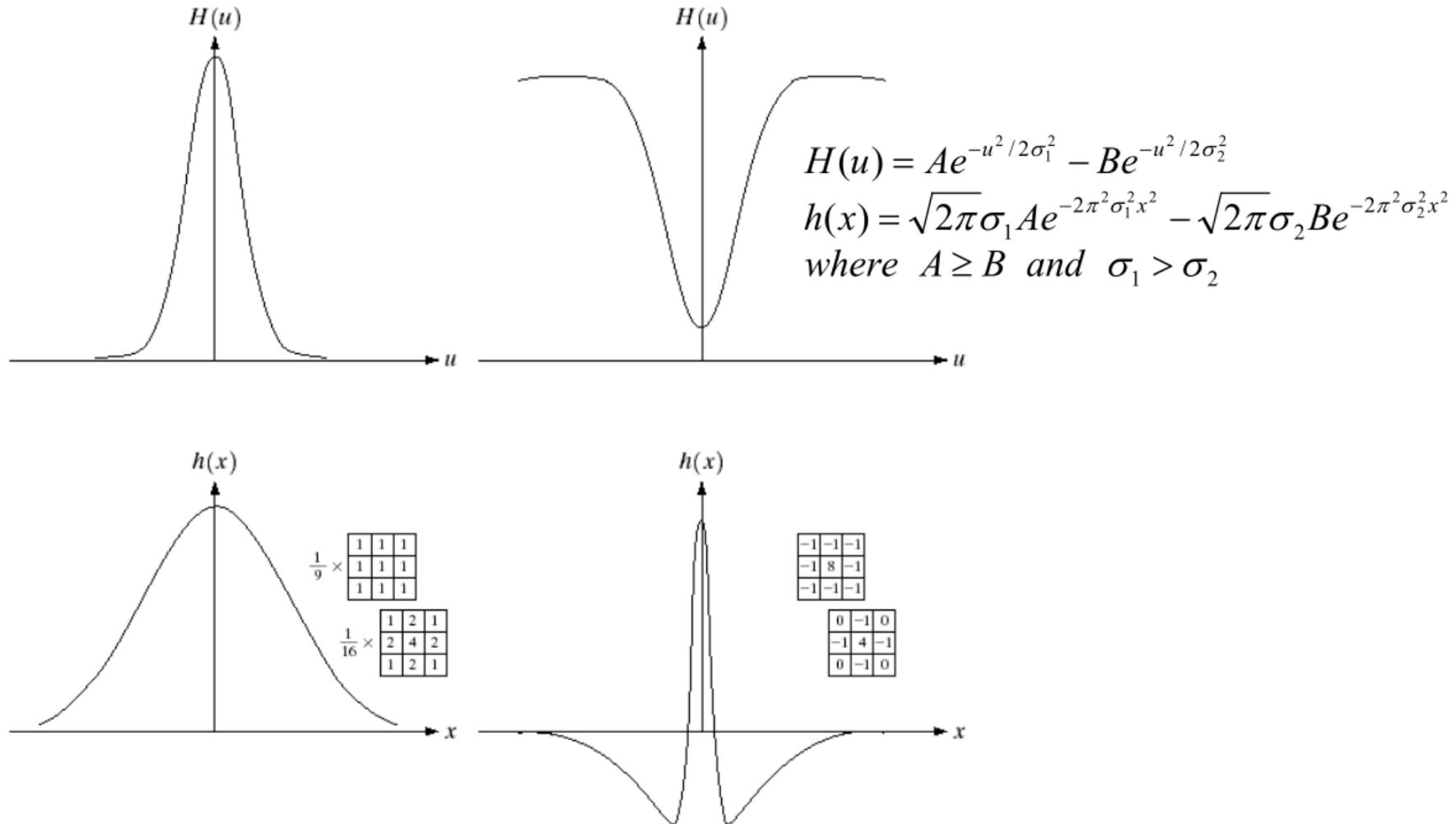
## □ Gaussian filters in spatial and frequency domain

$$H(u) = Ae^{-u^2/2\sigma^2} \Leftrightarrow h(x) = \sqrt{2\pi}\sigma Ae^{-x^2/2\alpha^2} \quad \text{where } \alpha = \frac{1}{2\pi\sigma}$$

$$H(u) = G(u; \sigma) \Leftrightarrow h(x) = \sqrt{2\pi}\sigma G(x; \frac{1}{2\pi\sigma})$$



# Filtering in Frequency Domain



# Smoothing Frequency-Domain Filters

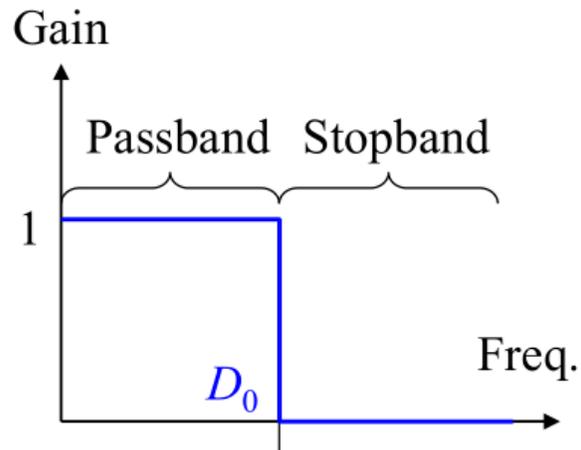
## □ Ideal Lowpass Filter

Filtering in Frequency Domain

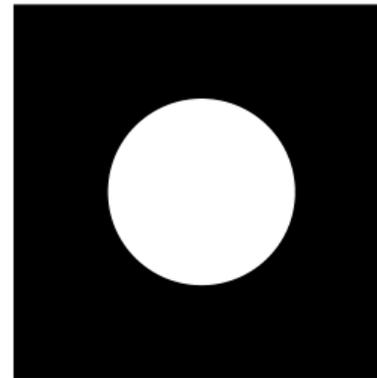
$$H(u, v) = \begin{cases} 1 & \text{if } D(u, v) \leq D_0 \\ 0 & \text{if } D(u, v) > D_0 \end{cases}$$

Cutoff Frequency

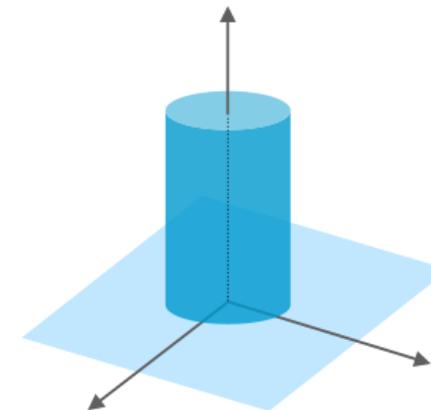
$$\text{where } D(u, v) = \left[ (u - M/2)^2 + (v - N/2)^2 \right]^{1/2}$$



1D Ideal Lowpass Filter



2D ILPF for Fourier spectrum



# Smoothing Frequency-Domain Filters

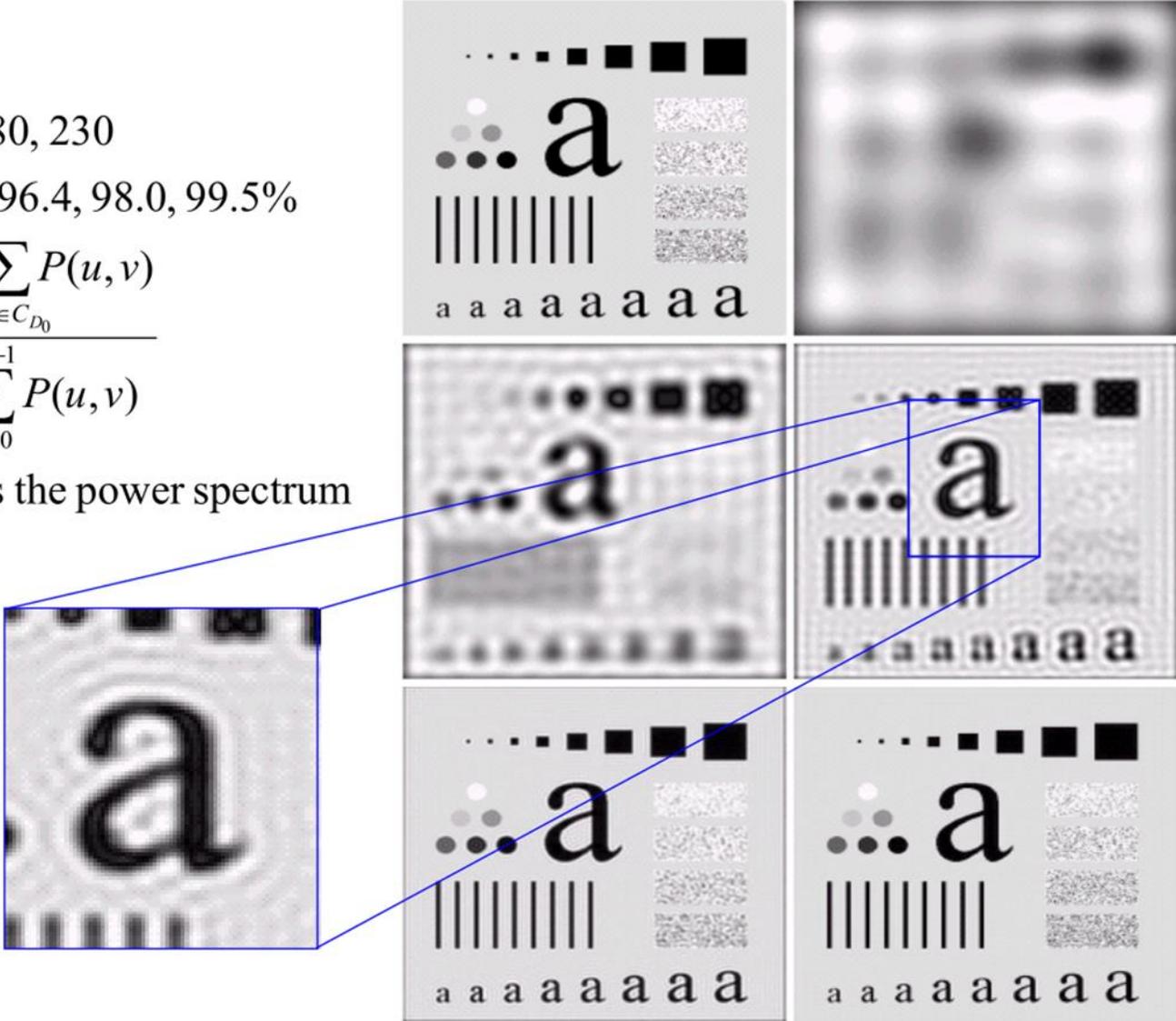
□ (Example)

$D_0 = 5, 15, 30, 80, 230$   
 $\alpha = 92.0, 94.6, 96.4, 98.0, 99.5\%$

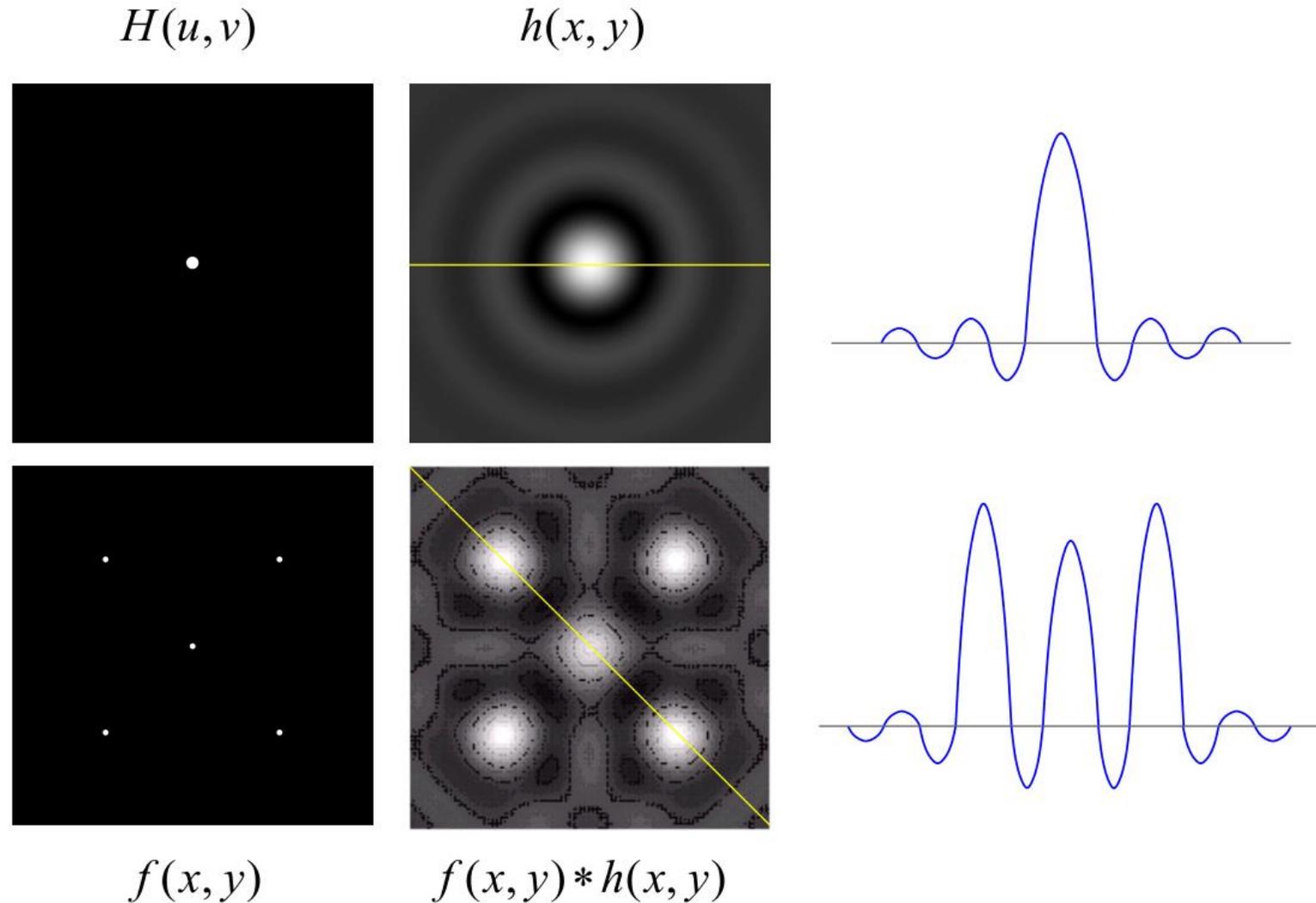
$$\alpha = \frac{100 \sum_{u,v \in C_{D_0}} P(u,v)}{\sum_{u=0}^{M-1} \sum_{v=0}^{N-1} P(u,v)}$$

where  $P(u, v)$  is the power spectrum

Ringling



# Smoothing Frequency-Domain Filters

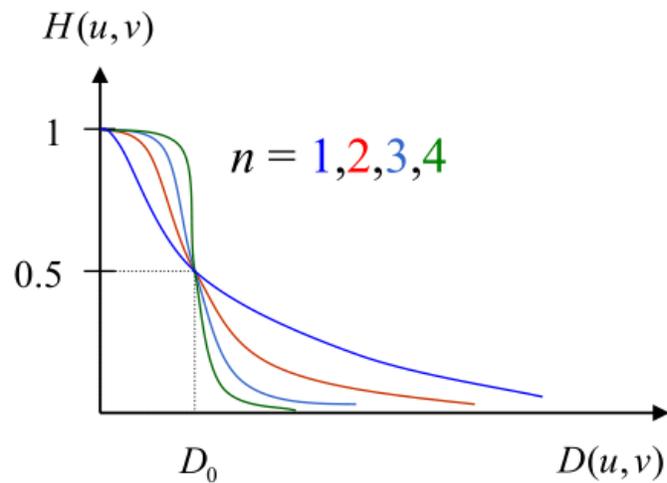


# Smoothing Frequency-Domain Filters

## □ Butterworth Lowpass Filter

$$H(u, v) = \frac{1}{1 + [D(u, v) / D_0]^{2n}}$$

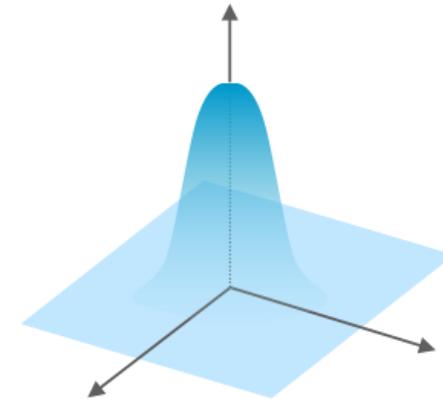
$$\text{where } D(u, v) = [(u - M / 2)^2 + (v - N / 2)^2]^{1/2}$$



1D Butterworth Lowpass Filter



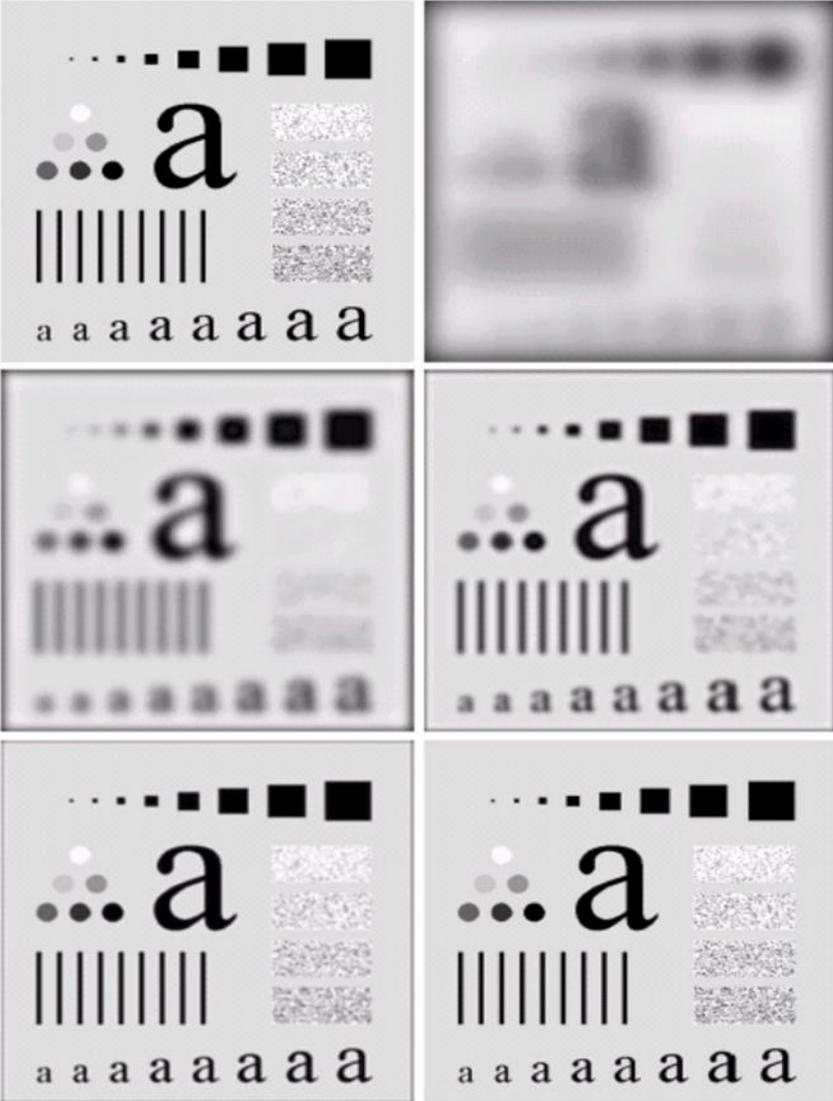
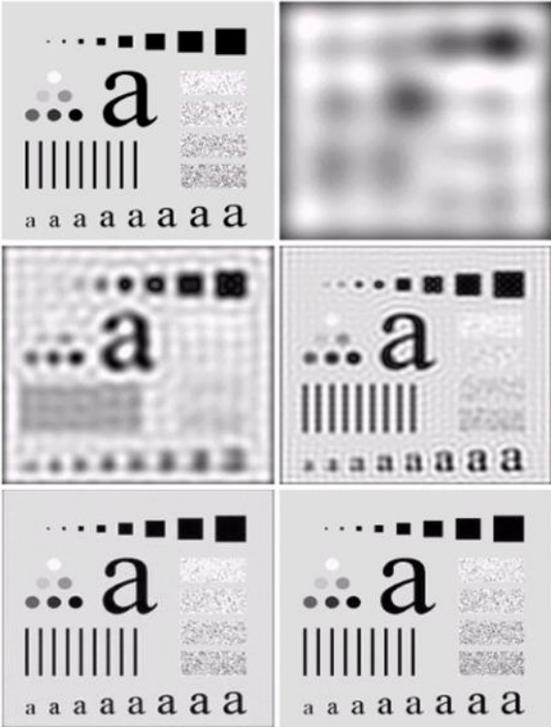
2D BLPF for Fourier spectrum



# Smoothing Frequency-Domain Filters

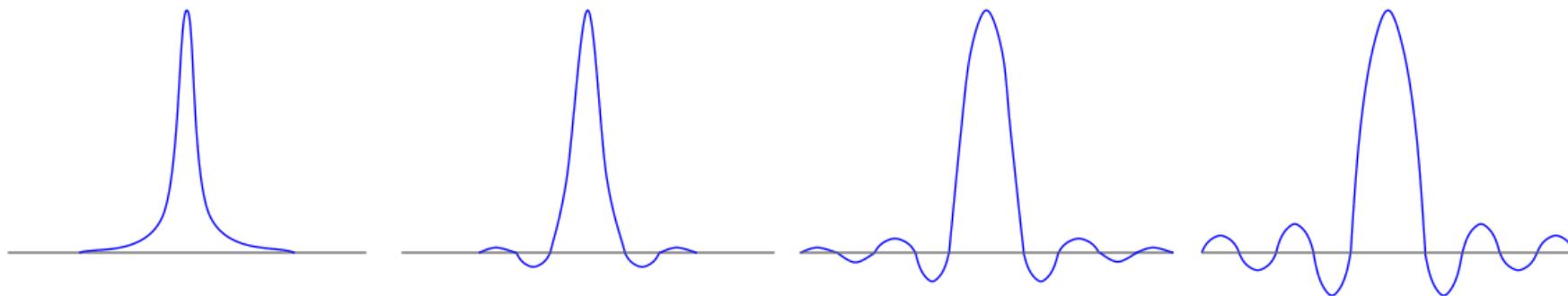
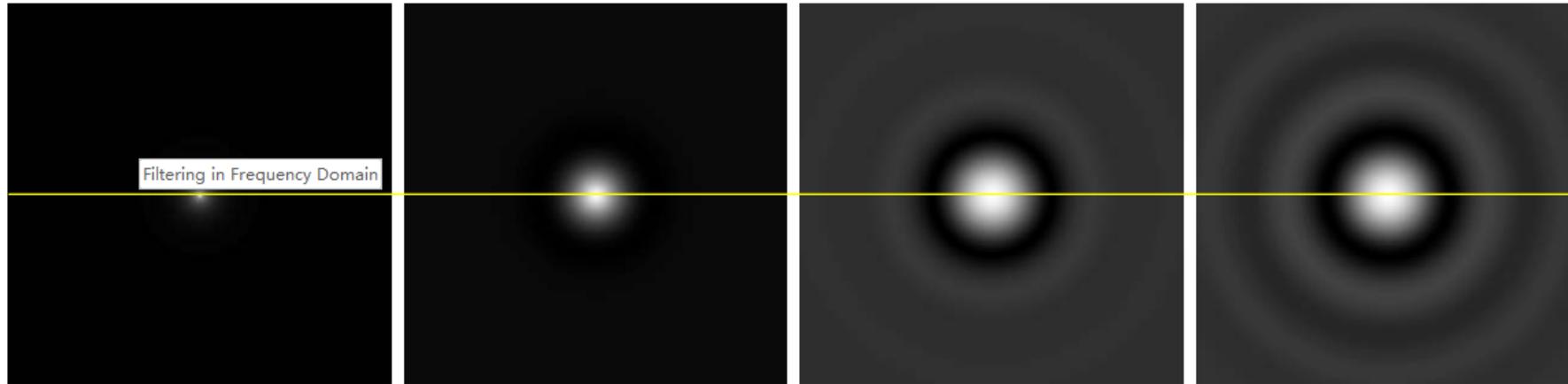
□ (Example)

$$D_0 = 5, 15, 30, 80, 230$$



# Smoothing Frequency-Domain Filters

$h(x, y)$



$n = 1$

$n = 2$

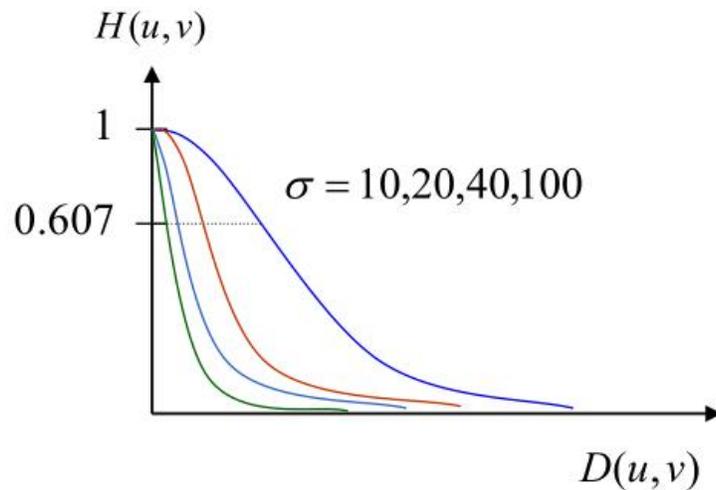
$n = 5$

$n = 20$

# Smoothing Frequency-Domain Filters

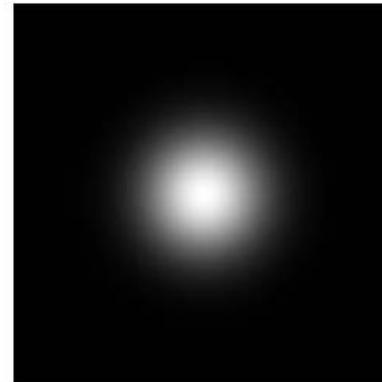
## □ Gaussian Lowpass Filter

$$H(u, v) = e^{-D^2(u, v)/2\sigma^2}$$

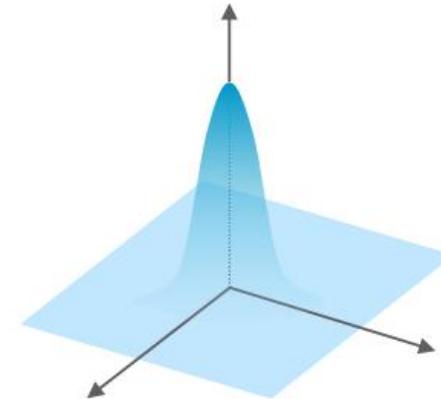


1D Gaussian Lowpass Filter

$$H(u, v)|_{D=\sigma} = e^{-1/2} \approx 0.607$$

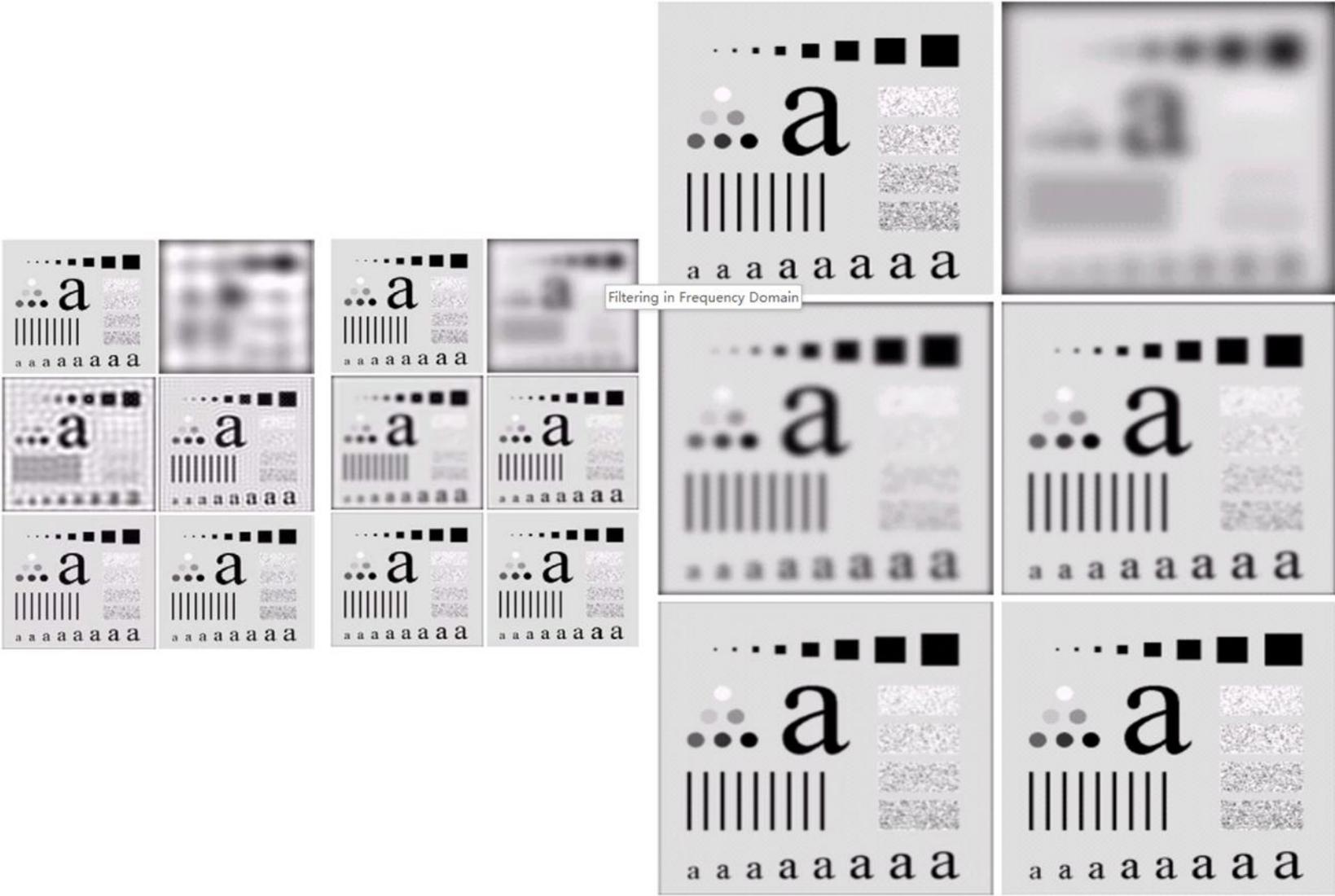


2D GLPF for Fourier spectrum



# Smoothing Frequency-Domain Filters

□ (Example)

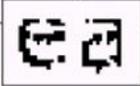


# Smoothing Frequency-Domain Filters

## □ Additional Examples



Historically, certain computer programs were written using only two digits rather than four to define the applicable year. Accordingly, the company's software may recognize a date using "00" as 1900 rather than the year 2000.

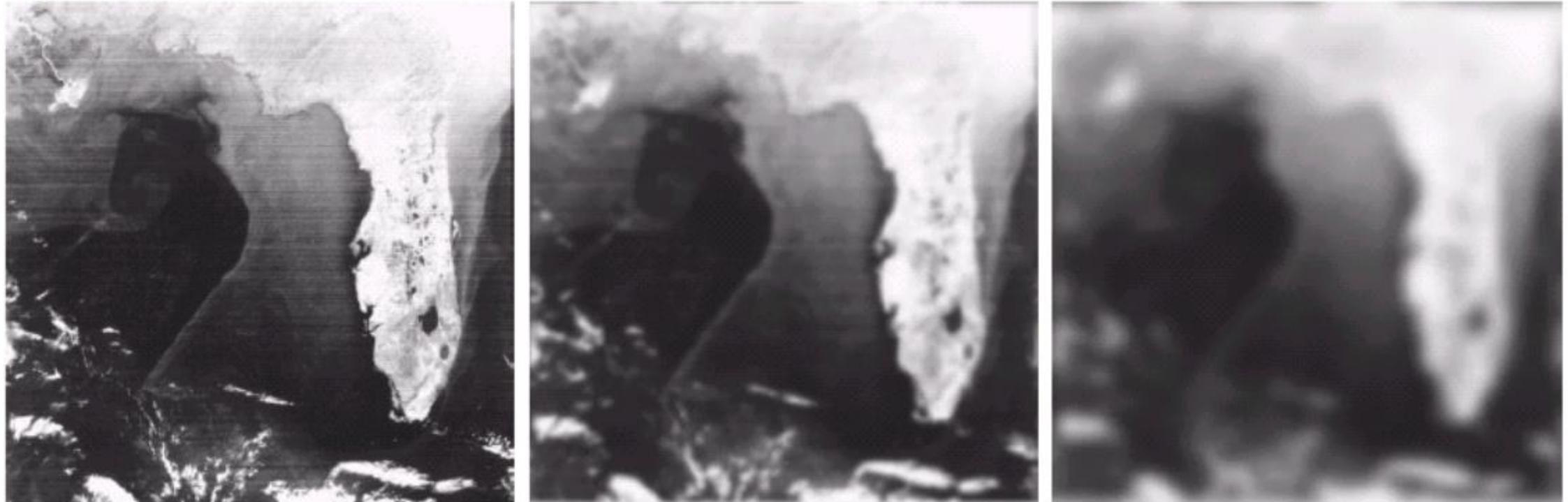


Historically, certain computer programs were written using only two digits rather than four to define the applicable year. Accordingly, the company's software may recognize a date using "00" as 1900 rather than the year 2000.



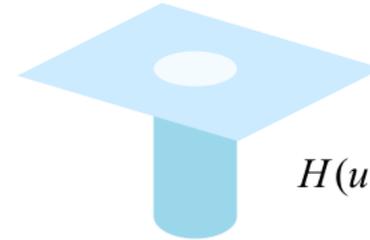
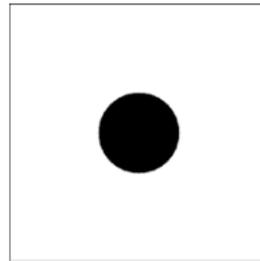
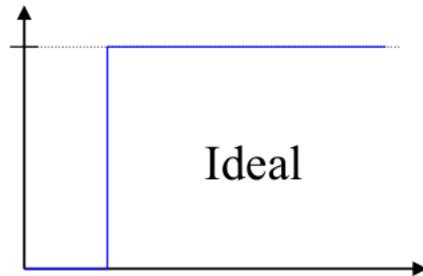
# Smoothing Frequency-Domain Filters

## □ Additional Examples

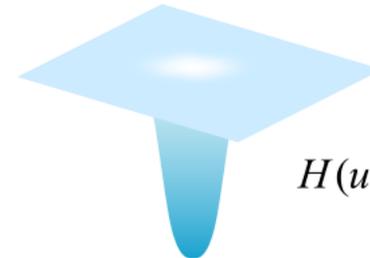
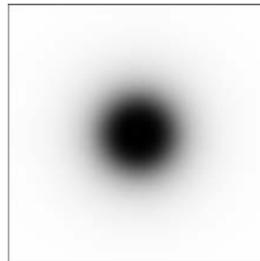
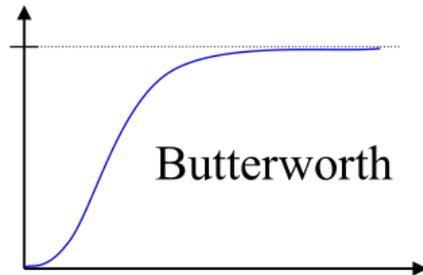


# Sharpening Frequency Domain Filters

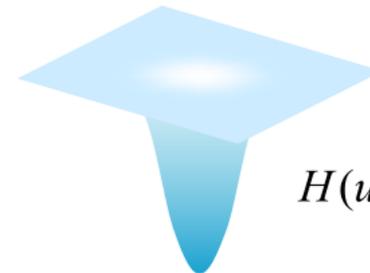
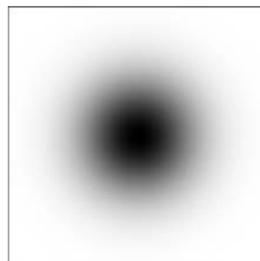
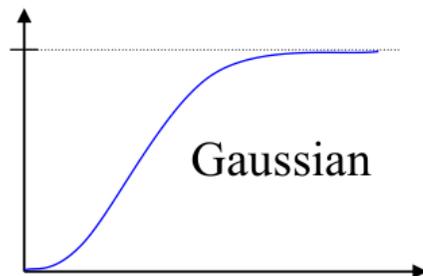
$$H_{hp}(u, v) = 1 - H_{lp}(u, v)$$



$$H(u, v) = \begin{cases} 0 & \text{if } D(u, v) \leq D_0 \\ 1 & \text{if } D(u, v) > D_0 \end{cases}$$



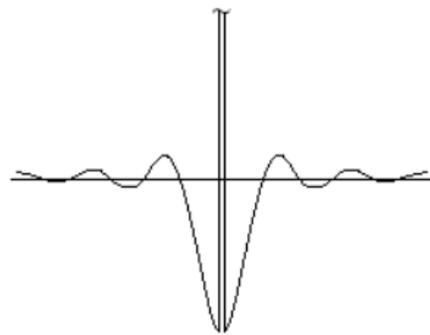
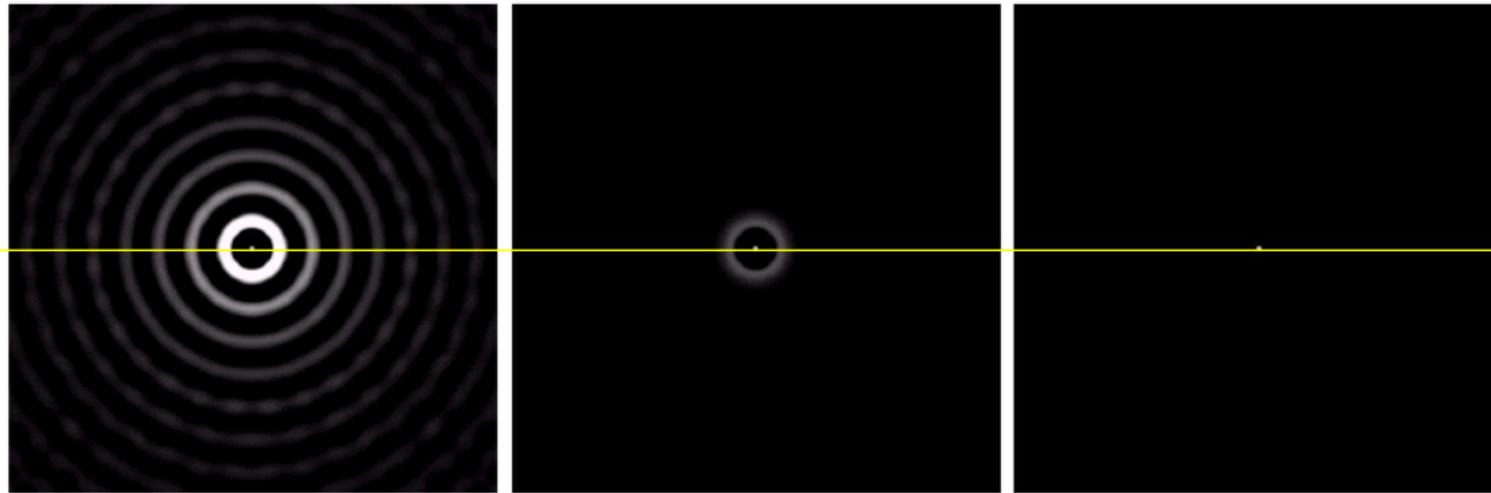
$$H(u, v) = \frac{1}{1 + [D_0 / D(u, v)]^{2n}} \quad \star$$



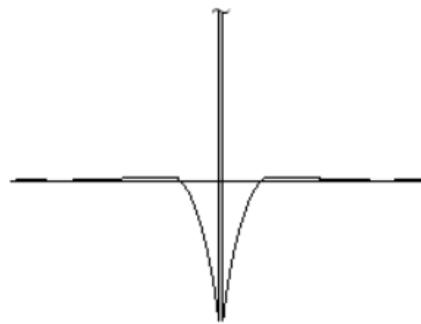
$$H(u, v) = 1 - e^{-D^2(u, v) / 2D_0^2}$$

# Sharpening Frequency Domain Filters

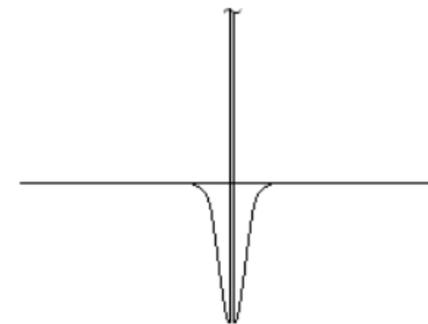
$h(x, y)$



Ideal

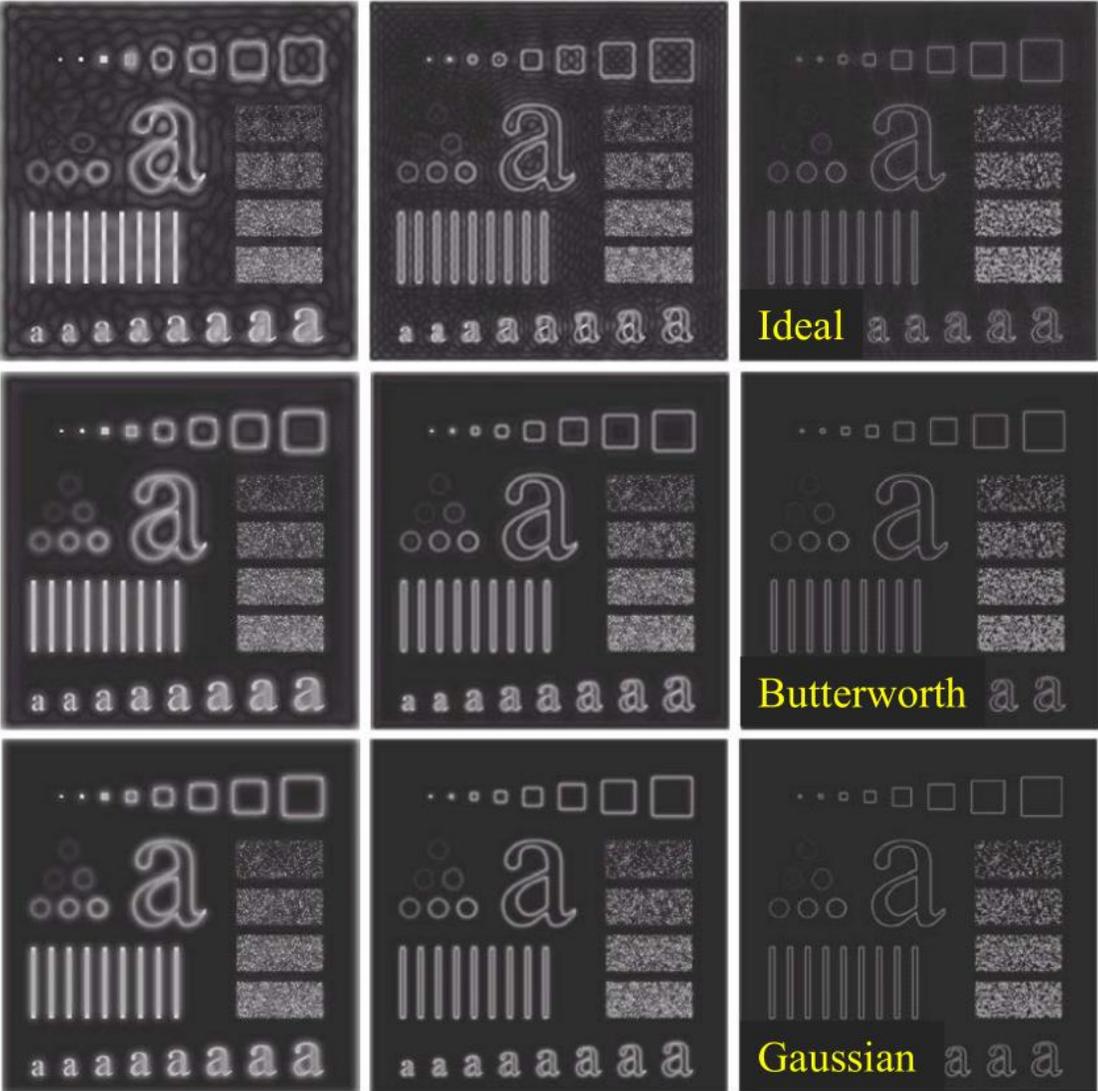


Butterworth



Gaussian

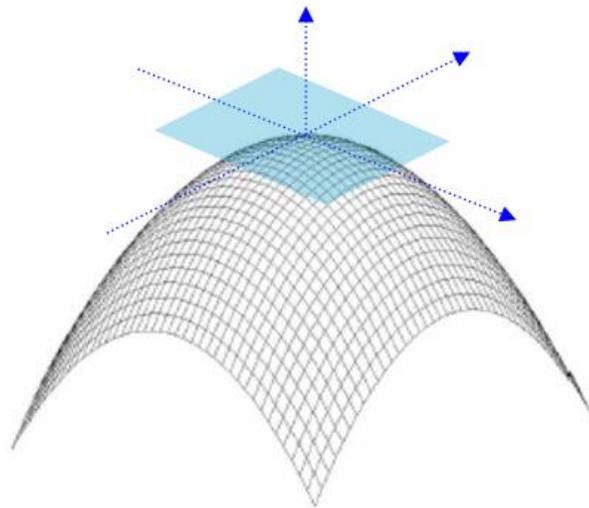
# Sharpening Frequency Domain Filters



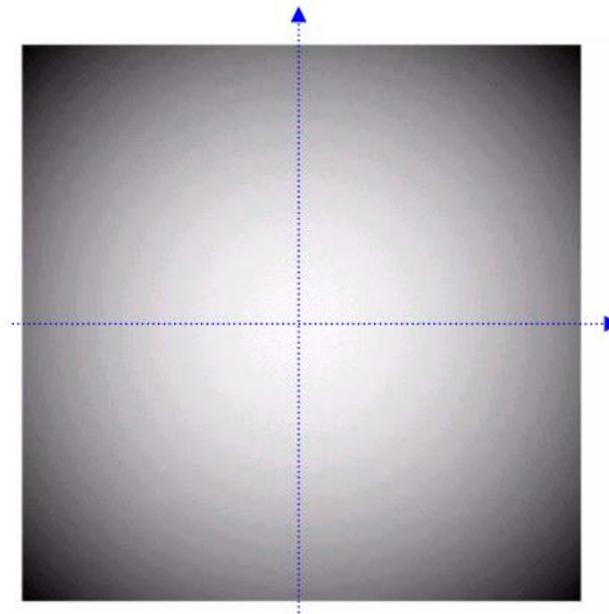
# Sharpening Frequency Domain Filters

## □ Laplacian in frequency domain

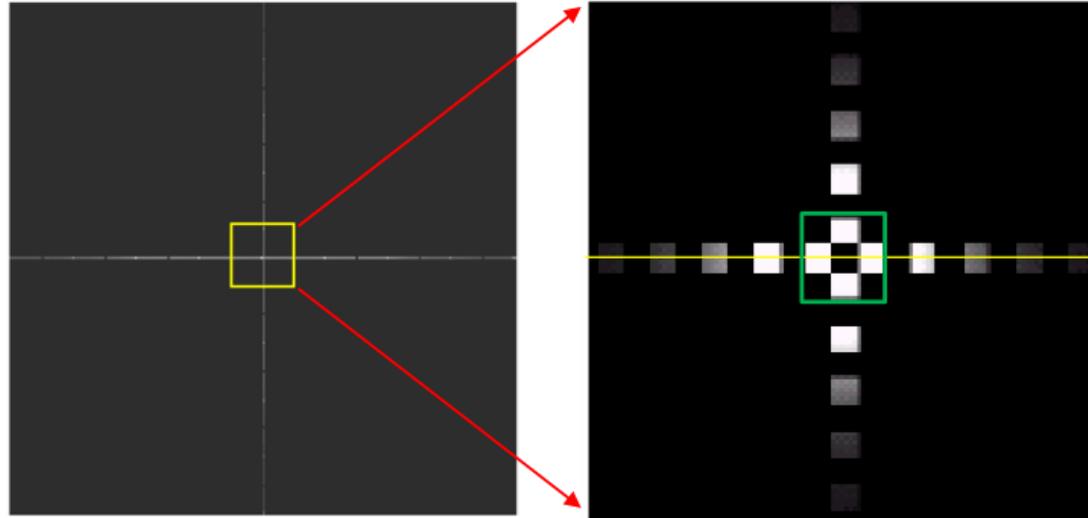
$$\mathfrak{F}[\nabla^2 f(x, y)] = \mathfrak{F}\left[\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2}\right] \longleftarrow \mathfrak{F}\left[\frac{d^n f(x)}{dx^n}\right] = (ju)^n F(u)$$
$$= (ju)^2 F(u, v) + (jv)^2 F(u, v) = -(u^2 + v^2)F(u, v)$$



$$H(u, v) = -(u^2 + v^2)$$

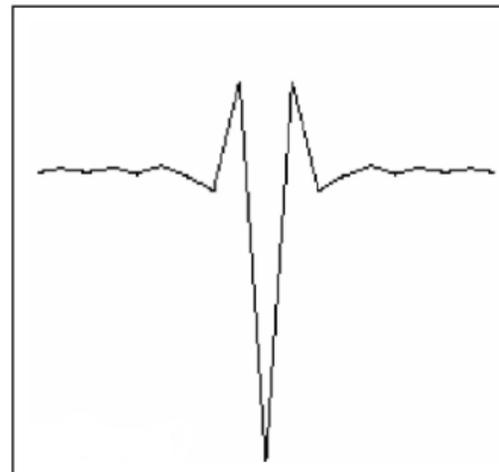


# Sharpening Frequency Domain Filters



0	1	0
1	-4	1
0	1	0

$$h(x, y) = \mathcal{F}^{-1}(-(u^2 + v^2))$$



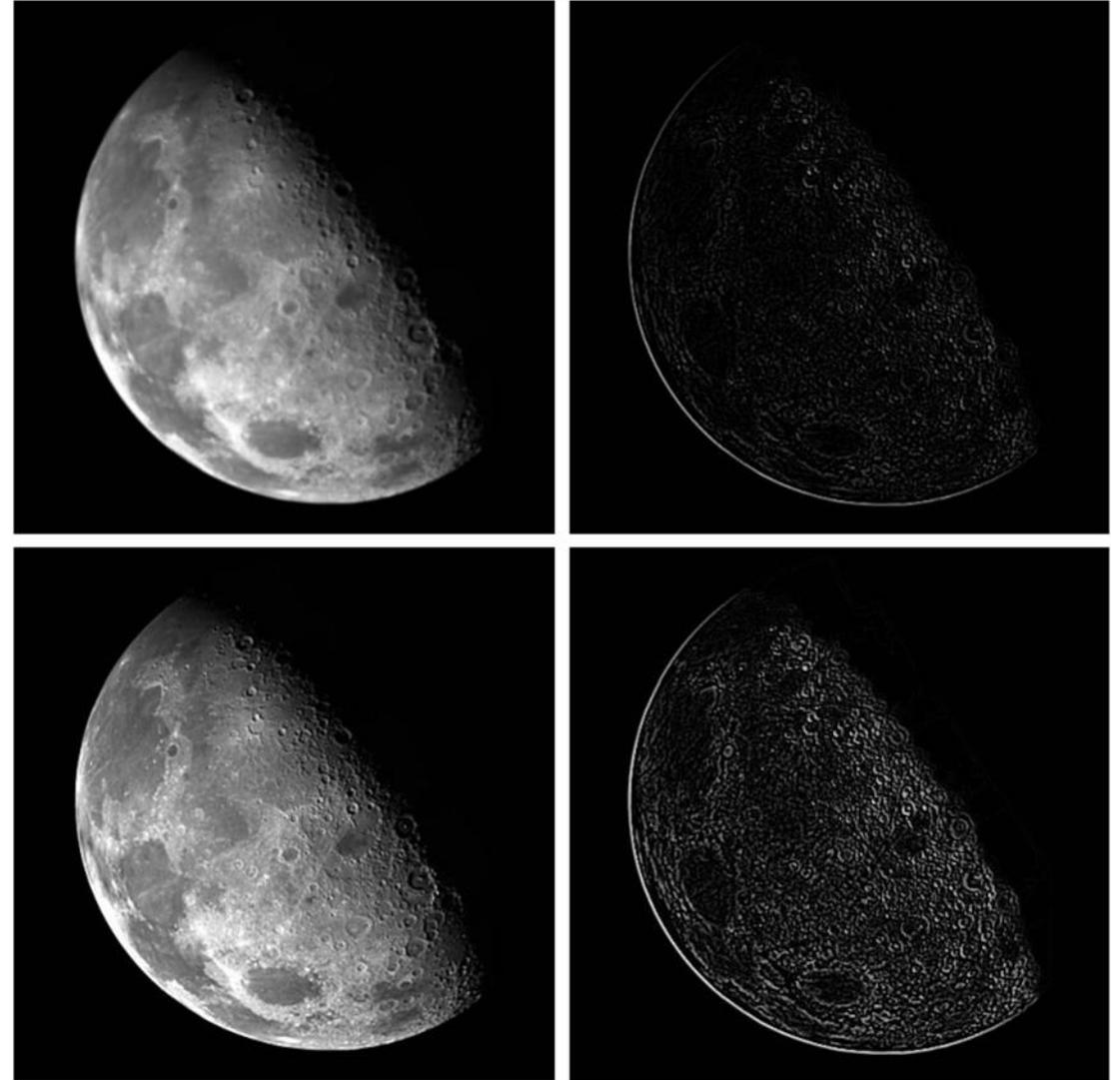
# Sharpening Frequency Domain Filters

## □ (Example)

$$g(x, y) = f(x, y) - \nabla^2 f(x, y)$$

$$G(u, v) = F(u, v) + (u^2 + v^2)F(u, v) = [1 + (u^2 + v^2)]F(u, v)$$

$$H(u, v) = 1 + (u^2 + v^2)$$



# Sharpening Frequency Domain Filters

## □ Unsharp Masking and Highpass Filtering

- Unsharp masking generates a sharp image by subtracting from an image a blurred version of itself
- Highpass filtering can be considered as an unsharp masking

$$f_{usm}(x, y) = f(x, y) - kf_{lp}(x, y)$$

$$\begin{aligned} F_{usm}(u, v) &= F(u, v) - kF_{lp}(u, v) = F(u, v) - kH_{lp}(u, v)F(u, v) \\ &= (1 - k)F(u, v) + k[1 - H_{lp}(u, v)]F(u, v) \\ &= (1 - k)F(u, v) + kH_{hp}(u, v)F(u, v) \end{aligned}$$

$$H_{usm}(u, v) = (1 - k) + kH_{hp}(u, v)$$

$$F_{hp}(u, v) = H_{hp}(u, v) F(u, v) \quad ; \quad k = 1$$

# Sharpening Frequency Domain Filters

## □ High-Boost Filtering

- Generalization of unsharp masking

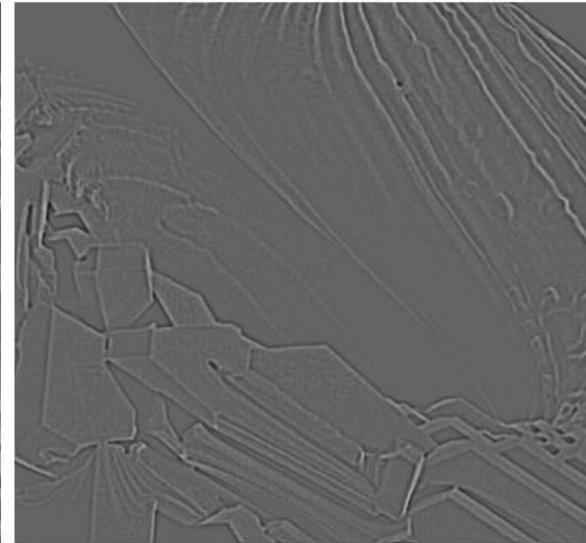
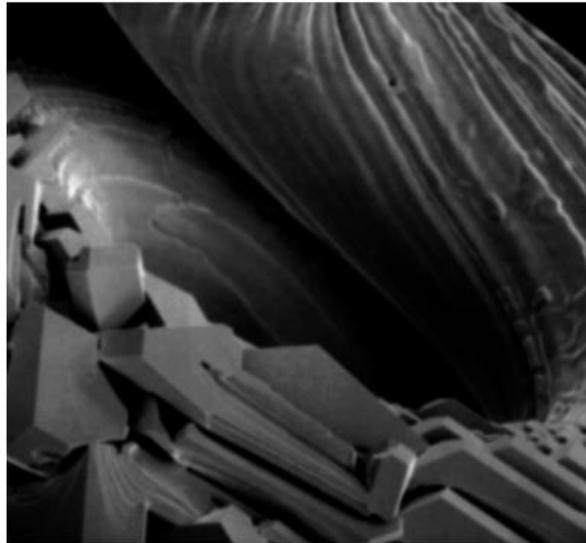
$$\begin{aligned}f_{hb}(x, y) &= Af(x, y) - f_{lp}(x, y) \\ &= (A-1)f(x, y) + f_{hp}(x, y)\end{aligned}$$

$$\begin{aligned}F_{hb}(u, v) &= (A-1)F(u, v) + H_{hp}(u, v)F(u, v) \\ &= \left[ (A-1) + H_{hp}(u, v) \right] F(u, v)\end{aligned}$$

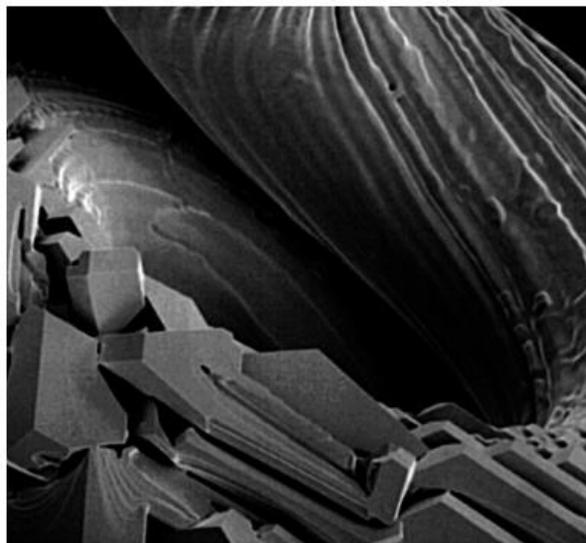
$$H_{hb}(u, v) = (A-1) + H_{hp}(u, v)$$

$$H_{usm}(u, v) = (1-k) + kH_{hp}(u, v)$$

# Sharpening Frequency Domain Filters



$A = 1$



$A = 2$



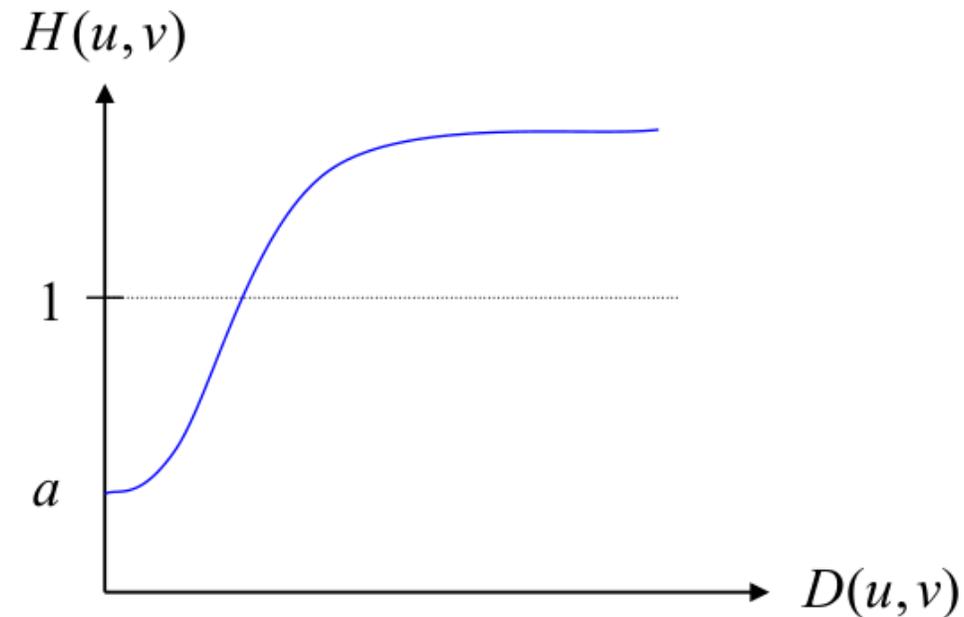
$A = 2.7$

# Sharpening Frequency Domain Filters

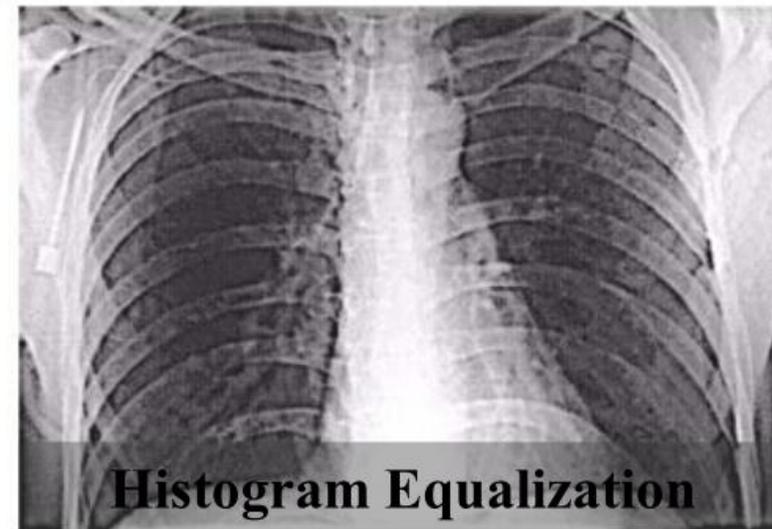
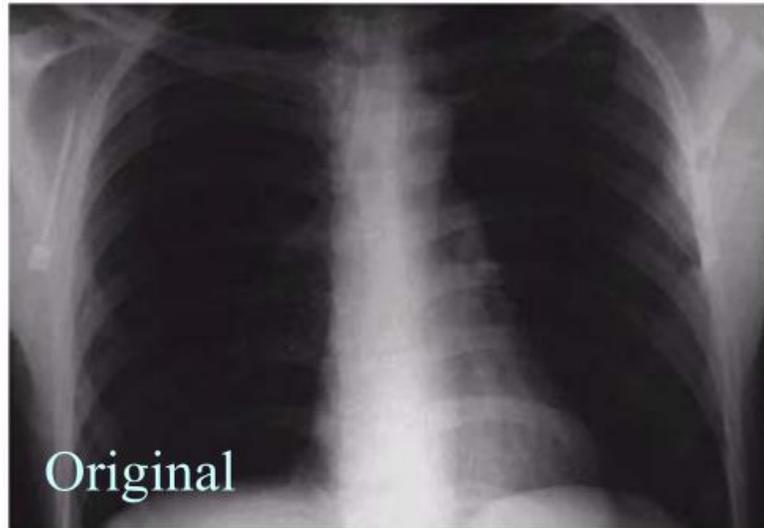
## □ High Frequency Emphasis Filter

$$H_{hfe}(u, v) = a + bH_{hp}(u, v)$$

where  $0.25 \leq a \leq 0.5$  and  $1.5 \leq b \leq 2.0$  typically



# Sharpening Frequency Domain Filters



# Summary

---

- ❑ Fourier Transform
  - ❑ Filtering in Frequency Domain
  - ❑ Smoothing Frequency Domain Filters
  - ❑ Sharpening Frequency Domain Filters
- 
- ❑ Next: Image Restoration and Reconstruction



# Thank You!